Self-duality and Exceptional Geometry

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The local isomorphism between the special orthogonal group SO(4) and the product $SO(3) \times SO(3)$ manifests itself in the conformally invariant decomposition of the bundle of 2-forms

$$\Lambda^2 T^* M = \Lambda_+^2 T^* M \oplus \Lambda_-^2 T^* M$$

over an oriented Riemannian 4-manifold M. There is a corresponding decomposition of the Weyl curvature tensor $W = W_+ + W_-$, and M is said to be *self-dual* if $W_- = 0$. If M is compact, its signature is given by

$$\tau = \frac{1}{3}p_1 = \frac{1}{12\pi^2} \int_M (|W_+|^2 - |W_-|^2)v,$$

where v is the volume form. Consequently, if M is self-dual but not conformally flat, then $\tau > 0$.

Self-duality is the integrability condition for a natural almost complex structure on the 6-dimensional sphere bundle of $\Lambda_-^2 T^* M$ [1]. Motivated in part by this result, we study the 7-dimensional total space X of $\Lambda_-^2 T^* M$, and characterize curvature conditions on M by means of differential relations between invariant forms on X. First though, we define the exceptional Lie group G_2 using the inclusion $SO(4) \subset G_2$, corresponding to a splitting of dimensions 7 = 3 + 4. This enables us to construct a family of G_2 -structures on X, which amounts to assigning a metric and vector cross product on each tangent space.

There are only two exceptions in the list of holonomy groups of irreducible non-symmetric Riemannian manifolds, namely G_2 and Spin(7) [2,3,5,11]. This explains the importance of G_2 -structures, which, in the light of [7], seem to be a little richer than their Spin(7) counterparts. An examination of the structure on X leads us to exhibit there a Riemannian metric with holonomy group G_2 , when M is the self-dual Einstein manifold S^4 or $\mathbb{C}P^2$. No such complete metrics were previously known. This, and analogous examples with holonomy G_2 and Spin(7), are the subject of a forthcoming joint paper with R. L. Bryant.

1. Definition of G_2

Let V denote an oriented n-dimensional vector space with a positive definite inner product <,>. The inner product extends to one on $\Lambda^k V^*$, and together with the orientation defines a unit volume form $v \in \Lambda^n V^*$ and an isomorphism $*: \Lambda^k V^* \to \Lambda^{n-k} V^*$, where

$$\sigma(*\tau) = <\sigma, \tau > \upsilon, \qquad \sigma, \tau \in \Lambda^k V^*. \tag{1}$$

Here and in the sequel, an exterior product of differential forms is denoted by their juxtaposition.

Now take n=4 and k=2. Then * is an involution on Λ^2V^* , and we consider the 7-dimensional space

$$A = \Lambda_{-}^{2} V^{*} \oplus V^{*}.$$

where $\Lambda_{-}^{2}V^{*}$ is the -1-eigenspace of *. If $\{e^{4}, e^{5}, e^{6}, e^{7}\}$ is an oriented orthonormal basis of V^{*} , then $\Lambda_{-}^{2}V^{*}$ is the span of

$$e^{1} = e^{4}e^{5} - e^{6}e^{7}, \quad e^{2} = e^{4}e^{6} - e^{7}e^{5}, \quad e^{3} = e^{4}e^{7} - e^{5}e^{6}.$$
 (2)

Regarding now e^1, \ldots, e^7 as all elements of A, rather than $\Lambda^2 A$, we set

$$\varphi' = e^{1}e^{2}e^{3}$$

$$\varphi'' = e^{1}(e^{4}e^{5} - e^{6}e^{7}) + e^{2}(e^{4}e^{6} - e^{7}e^{5}) + e^{3}(e^{4}e^{7} - e^{5}e^{6}).$$

Then $\varphi = \varphi' + \varphi''$ is the sum of 7 simple 3-forms on a 7-dimensional vector space, and has the following well-known property (see [5]).

Proposition 1 $G_2 = \{g \in GL(V) : g^*\varphi = \varphi\}$ is a compact Lie group of dimension 14.

Proof. G_2 is defined above as a closed subgroup of GL(V) containing SO(4). Decreeing $\{e^1, \ldots, e^7\}$ to be an oriented orthonormal basis of A defines an action of SO(7) with Lie algebra

$$so(7) \cong \Lambda^2 A \cong \Lambda^2(\Lambda_-^2 V^*) \oplus (\Lambda_-^2 V^* \otimes V^*) \oplus \Lambda^2 V^*$$
$$\cong \Lambda_-^2 V^* \oplus (V^* \oplus K) \oplus (\Lambda_+^2 V^* \oplus \Lambda_-^2 V^*). \tag{3}$$

Here K denotes the 8-dimensional subspace of $\Lambda_-^2 V^* \otimes V^*$ of elements with zero contraction; for example K contains $e^1 \otimes e^4 + e^2 \otimes e^7$ which defines a skew-symmetric endomorphism of V annihilating φ . Hence the Lie algebra \mathcal{G}_2 of G_2 contains K, not to mention $\Lambda_+^2 V^*$ and one copy of $\Lambda_-^2 V^*$. Now $S^2 A \cong \mathbf{R} \oplus S_0^2 A$, where

$$S_0^2 A \cong S_0^2(\Lambda_-^2 V^*) \oplus \mathbf{R} \oplus V^* \oplus K \oplus S_0^2 V^*$$

is the space of traceless symmetric endomorphisms of A, decomposed into SO(4)-modules. Consideration of the action of $K \subset \mathcal{G}_2$ shows that S_0^2A is G_2 -irreducible. Thus

$$\mathcal{G}_2 = \mathsf{so}(4) \oplus K$$

and it is not hard to check that $G_2 \subset SO(7)$. Q.E.D.

The form φ defines by contraction a two-fold vector cross product

$$m: \Lambda^2 A \longrightarrow A,$$
 (4)

of the sort that exists only on a space of dimension 3 or 7 [4]. Using m, $\mathbf{O} = \mathbf{R} \oplus A$ can be identified with the alternative algebra of Cayley numbers, to give the description of G_2 as the group of automorphisms of \mathbf{O} . The subspace $\mathbf{H} = \mathbf{R} \oplus \Lambda^2_- V^*$ corresponds to a quaternionic subalgebra, and K may be identified with the tangent space of the quaternionic symmetric space $G_2/SO(4)$, parametrizing all quaternionic subalgebras in \mathbf{O} [9].

Like S_0^2A , the G_2 -modules A and \mathcal{G}_2 are irreducible, and from (4), the orthogonal complement \mathcal{G}_2^{\perp} of \mathcal{G}_2 in so(7) must be isomorphic to A. The derivative

$$\delta : \operatorname{End}(A) \cong A \otimes A \hookrightarrow \Lambda^3 A$$

of the action of GL(V) on φ has kernel \mathcal{G}_2 . It follows that the orbit $GL(V)/G_2$ containing φ is open in Λ^3A ; in fact there is just one other open orbit, containing the form $\varphi' - \varphi''$, with stabilizer the non-compact form G^* [5]. Anyway, the above remarks establish

Proposition 2 $\Lambda^2 A \cong \mathcal{G}_2 \oplus A$, $\Lambda^3 A \cong \mathbf{R} \oplus S_0^2 A \oplus A$.

2. Four-dimensional Riemannian Geometry

Let M be an oriented Riemannian 4-manifold. We shall now use the symbols e^4, e^5, e^6, e^7 to denote elements of an oriented orthonormal basis of 1-forms on an open set U of M. Accordingly e^1, e^2, e^3 defined by (2) form a basis of sections over U of $\Lambda^2_-T^*M$. The Levi Civita connection on M induces a covariant derivative ∇ on this vector bundle, and we set

$$\nabla e^i = \Sigma \,\omega^i_j \otimes e^j, \qquad \Omega^i_j = d\omega^i_j - \Sigma \,\omega^i_k \omega^k_j.$$

Summations here and below are exclusively over the range of indices 1,2,3.

Let X denote the total space of $\Lambda_{-}^{2}T^{*}M$; its cotangent space at x admits a splitting

$$T_x^* X = V^o \oplus H^o, \tag{5}$$

where H^o is the annihilator of the horizontal subspaces defined by ∇ , and $V^o = \pi^* T_m^* M$, $m = \pi(x)$. A local section $\sum a^i e^i$ of $\Lambda_-^2 T^* M$ is covariant constant iff $\sum (da^i + \sum a^j \omega_i^j) \otimes e^i = 0$, so H^o is spanned by 1-forms

$$f^i = da^i + \sum a^j \pi^* \omega_i^j,$$

where a^1, a^2, a^3 are now interpreted as fibre coordinate functions on X. Of course V^o is spanned by $\pi^*e^4, \pi^*e^5, \pi^*e^6, \pi^*e^7$.

Omitting the symbol π^* , consider the following invariant forms, defined globally on X, independently of the choice of basis:

$$r = \sum (a^{i})^{2}$$

$$dr = 2\sum a^{i}f^{i}$$

$$\alpha = \sum a^{i}e^{i}$$

$$d\alpha = \sum e^{i}f^{i}, \quad \beta = f^{1}f^{2}f^{3}$$

$$\gamma = e^{1}f^{2}f^{3} + e^{2}f^{3}f^{1} + e^{3}f^{1}f^{2}, \quad v = -\frac{1}{6}\sum e^{i}e^{i}$$

For example r is simply the radius squared, α is the tautological 2-form on X, and $v = e^4 e^5 e^6 e^7$ is the pullback of the volume form on M.

Proposition 3 (i) M is self-dual if and only if $d\gamma = 2tvdr$ for (the pullback of) some scalar function t on M; (ii) M is self-dual and Einstein if and only if $d\beta = \frac{1}{2}td\alpha dr$, for some constant t. If t exists in either case, it equals $\frac{1}{12}$ of the scalar curvature of M.

Proof. We refer the reader to [1] for basic properties of the curvature tensor of a Riemannian 4-manifold. The curvature of the induced connection on the bundle $\Lambda_{-}^{2}T^{*}M$ is determined by the Ricci tensor, and the half W_{-} of the Weyl tensor which may be regarded as a section of $\Lambda_{-}^{2}T^{*}M \otimes \Lambda_{-}^{2}T^{*}M$. Moreover M is self-dual and Einstein iff

$$\Omega_2^1 = te^3, \quad \Omega_3^2 = te^1, \quad \Omega_1^3 = te^2,$$
(6)

where $t = \frac{1}{12}$ (scalar curvature). Since the trace-free Ricci tensor essentially belongs to $\Lambda_-^2 T^* M \otimes \Lambda_+^2 T^* M$, M is self-dual iff (6) holds modulo elements of $\Lambda_+^2 T^* M$. The proposition is now the result of a computation involving the formulae

$$de^i = \Sigma \, \omega^i_j e^j, \qquad df^i = \Sigma (f^j \omega^j_i + a^j \Omega^j_i).$$
 Q.E.D.

Motivated by section 1, we next consider the 3-form

$$\varphi = \lambda^3 \beta + \lambda \mu^2 d\alpha, \tag{7}$$

where λ and μ are scalar functions on X. Observe that

$$\varphi = E^1 E^2 E^3 + E^1 E^4 E^5 - E^1 E^6 E^7 + E^2 E^4 E^6 - E^2 E^7 E^5 + E^3 E^4 E^7 - E^3 E^5 E^6,$$

where E^i equals λf^i for i=1,2,3 and $\mu \pi^* e^i$ for i=4,5,6,7, and forms an oriented orthonormal basis of 1-forms for the underlying SO(7)-structure on X. In view of (1), we also have

$$*\varphi = E^{4}E^{5}E^{6}E^{7} + E^{2}E^{3}E^{6}E^{7} - E^{2}E^{3}E^{4}E^{5} + E^{3}E^{1}E^{7}E^{5} - E^{3}E^{1}E^{4}E^{6} + E^{1}E^{2}E^{5}E^{6} - E^{1}E^{2}E^{4}E^{7}$$

$$= \mu^{4}v - \lambda^{2}\mu^{2}\gamma. \tag{8}$$

Proposition 1 implies

Proposition 4 If λ and μ are strictly positive everywhere, (7) determines a G_2 -structure on X, i.e. a G_2 -subbundle P of the principal frame bundle of X, whose underlying Riemannian metric has the form $\lambda^2 g^V + \mu^2 g^H$ in terms of the splitting (5).

3. Torsion considerations

If D denotes the Levi Civita connection of the Riemannian metric in Proposition 4, the quantity $D\varphi$ measures the failure of the holonomy group to reduce to G_2 , i.e. the extent to which parallel transport does not preserve the principal subbundle P. Its properties were studied by Fernández and Gray in [7], and we first summarize their approach.

Choose any connection D that reduces to P, so that $D\varphi = 0$. Fix a frame $p \in P$ at the point $x = \pi(p) \in X$, and a vector $v \in T_xX$. The difference $D_v - \tilde{D}_v$ defines, relative to p, an element of the Lie algebra so(7). The same is true of $D_v \varphi = (D_v - \tilde{D}_v)\varphi$, but since this is independent of the choice of \tilde{D} , it actually belongs to the subspace \mathcal{G}_2^{\perp} . Therefore $(D\varphi)_x$ may be regarded as an element of

$$T_x^* X \otimes \mathcal{G}_2^{\perp} \cong A \otimes A \cong \mathbf{R} \oplus \mathcal{G}_2 \oplus S_0^2 A \oplus A.$$
 (9)

Let $W_1X \cong X \times \mathbf{R}$, W_2X , W_3X , $W_4X \cong TX \cong T^*X$ denote the vector bundles associated to P with fibre \mathbf{R} , \mathcal{G}_2 , S_0^2A , A respectively. Corresponding to (9), there is a decomposition

$$D\varphi = w_1 + w_2 + w_3 + w_4,$$

in which w_i is a section of W_iX . Now D is torsion-free, and there exist surjective homomorphisms

$$\begin{array}{cccc} a: T^*X \otimes \Lambda^3 T^*X & \longrightarrow & \Lambda^4 T^*X \cong W_1 X \oplus W_3 X \oplus W_4 X \\ a^*: T^*X \otimes \Lambda^3 T^*X & \longrightarrow & \Lambda^5 T^*X \cong W_2 X \oplus W_4 X, \end{array}$$

such that $d\varphi = a(D\varphi)$ and $d*\varphi = a^*(D\varphi)$ (cf. Proposition 2). Thus

Proposition 5 [7] With the above identifications, $d\varphi = (w_1, w_3, w_4)$, and $d*\varphi = (w_2, w_4)$, so $D\varphi = 0$ if and only if $d\varphi = 0 = d*\varphi$.

Call a differential form on X of type (p,q) if, at each point, it is built up from forms on the base of degree p and forms of degree q involving f^i . Endow X with the G_2 -structure of Proposition 4, with λ and μ arbitrary positive scalar functions on X. Then $d\varphi$, unlike $*\varphi$, has no component of type (4,0). Moreover $\varphi d\varphi = 0$, whence $d\varphi$ has no component in the subbundle $W_1X \subset \Lambda^4T^*X$, and we always have $w_1 = 0$. Further components of $D\varphi$ can be eliminated by a suitable choice of λ and μ .

Theorem (i) If M is self-dual, an open set of X admits a G_2 -structure with $D\varphi = w_3$; (ii) if M is self-dual and Einstein, an open set of X admits a G_2 -structure with $D\varphi = 0$.

Proof. We apply Proposition 3. If M is self-dual, we seek λ, μ such that

$$d*\varphi = d(\mu^4)\upsilon - d(\lambda^2\mu^2)\gamma - \lambda^2\mu^2 2t\upsilon dr,$$

vanishes. Taking $\lambda \mu = c = \text{constant}$, we obtain a solution

$$\mu = (2c^2tr + d)^{\frac{1}{4}}, \quad \lambda = c(2c^2tr + d)^{-\frac{1}{4}},$$
 (10)

where d is another constant. If M is also Einstein, then dt = 0 and

$$d\varphi = d(\lambda^3)\beta + \lambda^3 \frac{1}{2}td\alpha dr + d(\lambda\mu^2)d\alpha = 0.$$

Note that λ, μ can only be strictly positive on all of X if t is everywhere non-negative. Q.E.D.

In [7] it is shown that any minimally embedded hypersurface of \mathbf{R}^8 also has a G_2 -structure with $D\varphi = w_3$. A contrasting example with $D\varphi = w_2 \neq 0$ has been found in [6]. We remark that in general w_2 is the obstruction to the existence of a short elliptic complex

$$0 \to C^{\infty}(X) \xrightarrow{\operatorname{grad}} C^{\infty}(X, TX) \xrightarrow{\operatorname{curl}} C^{\infty}(X, TX) \xrightarrow{\operatorname{div}} C^{\infty}(X) \to 0,$$

on X whose operators are manufactured using D and (4) in analogy with the 3-dimensional case. Indeed, if $f \in C^{\infty}(X)$ is a function, and $v \in C^{\infty}(X, TX)$ is a vector field, $\operatorname{curl}(\operatorname{grad} f) = m(D \land (\operatorname{grad} f))$ vanishes identically, but $\operatorname{div}(\operatorname{curl} v)$ equals the contraction of Dv with w_2 . We conjecture that a complex of this sort can be defined on X, using only the self-dual conformal structure of M. Topological consequences of the existence of a self-dual metric with t non-negative have been given by LeBrun [10].

Self-dual Einstein metrics have been generated by quaternionic Kähler reduction [8]. However a theorem of Hitchin states that a complete Riemannian 4-manifold which is self-dual, Einstein and of positive scalar curvature is

necessarily isometric to the sphere S^4 , or the complex projective plane $\mathbb{C}P^2$ [3, 13.30]. In either of these two cases, the Riemannian metric

$$(2tr+1)^{-\frac{1}{2}}g^V + (2tr+1)^{\frac{1}{2}}g^H$$

on X corresponding to the solution (10) with c = d = 1 is complete, essentially because $\int_0^\infty (2tr+1)^{-\frac{1}{4}} d(r^{\frac{1}{2}})$ diverges. Because $D\varphi = 0$, the holonomy group H is contained in G_2 , which in turn implies that the Ricci tensor is zero [3]. Furthermore, the respective groups SO(5), SU(3) act as isometries on X with generic orbits of codimension 1. Consideration of the induced action on a hypothetical space of covariant constant 1-forms shows that X is locally irreducible, and it follows that $H = G_2$ [5]. In conclusion:

Corollary The total space of $\Lambda_{-}^{2}T^{*}S^{4}$ and $\Lambda_{-}^{2}T^{*}\mathbf{C}P^{2}$ admits a complete Ricci-flat Riemannian metric with holonomy equal to G_{2} .

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