

An arbitrary conic  $ax^2 + 2bxy + cy^2 + 2dx + 2ey + f = 0$  is the intersection of the plane  $z = 1$  with the quadric

$$ax^2 + cy^2 + fz^2 + 2eyz + 2d zx + 2bxy = 0,$$

equivalently

$$(x \ y \ z) \begin{pmatrix} a & b & d \\ b & c & e \\ d & e & f \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 0.$$

We can diagonalize the  $3 \times 3$  matrix by a rotation, and the equation becomes

$$\lambda_1 X^2 + \lambda_2 Y^2 + \lambda_3 Z^2 = 0.$$

If the eigenvalues  $\lambda_i$  are all non-zero, we may assume that  $\lambda_1, \lambda_2 > 0$  and  $\lambda_3 < 0$ , so that the quadric is an *elliptical cone*. It is easy to visualize plane sections of such a cone that are hyperbolas, ellipses, parabolas or two intersecting lines.

**Proposition.** Let  $\alpha, \ell$  be skew lines. If  $\ell$  is rotated around  $\alpha$  (as axis) then  $\ell$  sweeps out a hyperboloid (of one sheet).

**Example.** Take  $\alpha$  the  $z$ -axis and  $\ell$  (in parametric form) to be

$$(x, y, z) = (\underbrace{1, t, t}.)$$

Rotate  $\ell$  by applying the matrix  $\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$  to obtain

$$\ell_\theta = \{(\cos \theta - t \sin \theta, \sin \theta + t \cos \theta, t) : t \in \mathbb{R}\},$$

a line which (for each fixed  $\theta$ ) lies on the hyperboloid

$$x^2 + y^2 - z^2 = 1,$$

as does the line  $m_\theta$  with  $z = -t$  in place of  $z = t$ .

A cone is formed from straight lines which pass through its vertex and some fixed conic. For example,

$$\{(s, st^2, st) : s, t \in \mathbb{R}\}$$

joins the origin to a parabola in the plane  $x = 1$ . It consists of all the points of the quadric

$$z^2 = xy \quad \text{or} \quad X^2 - Y^2 - 2Z^2 = 0$$

(where  $x = (X-Y)/\sqrt{2}$  and  $y = (X+Y)/\sqrt{2}$  defines a rotation) minus the points  $(0, u, 0)$  for  $u \neq 0$ .

The image shows the two families of straight lines present in the saddle-shaped hyperbolic paraboloid  $z = xy$ . Each green line (drawn in the lecture and including the  $y$ -axis) is

$$\{(s, t, st) : t \in \mathbb{R}\}, \quad s \text{ constant},$$

and each red line (including the  $x$ -axis) is

$$\{(s, t, st) : s \in \mathbb{R}\}, \quad t \text{ constant}.$$

