## SUMMARY

A line r is determined by a vector  $\mathbf{p} = (A, B, C)$  parallel to it and a point  $P_0$  on it. If  $\mathbf{v}_0 = O\vec{P}_0 = (x_0, y_0, z_0)$ , a generic point P on r is

$$(x, y, z) = (x_0 + At, y_0 + Bt, z_0 + Ct), t \in \mathbb{R}.$$

Its position vector is

$$OP = \mathbf{v} = \mathbf{v}_0 + t\mathbf{p},$$

and so

 $\mathbf{v} \times \mathbf{p} = \mathbf{q}$ 

where **p** and  $\mathbf{q} = \mathbf{v}_0 \times \mathbf{p}$  are fixed vectors such that  $\mathbf{p} \cdot \mathbf{q} = 0$ .

Given two distinct lines  $r_1, r_2$ , there are three possibilities, namely they are

(i) *parallel* ( $p_1$ ,  $p_2$  are proportional), or

(ii) *incident* ( $r_1$ ,  $r_2$  intersect in a single point), or

(iii) *skew* (there is no plane that contains both  $r_1, r_2$ ).

Given equations for  $r_1$ ,  $r_2$  one must first check that they are neither coincident nor parallel, and then solve equations to see whether or not there exists a point of intersection.

In (ii), the plane containing  $r_1, r_2$  will have a normal vector

$$\mathbf{n}=\mathbf{p}_1\times\mathbf{p}_2.$$