

From Societies of Brains to Brains of Societies

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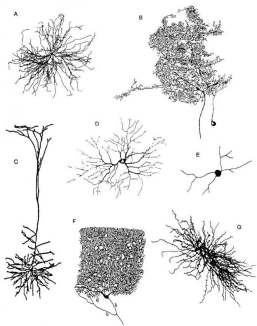
Cumberland Lodge, 19 Feb, 2022



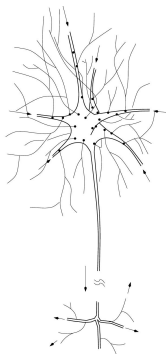
Outline

- 1 Neurons & Neural Networks
- 2 Information Processing & Learning
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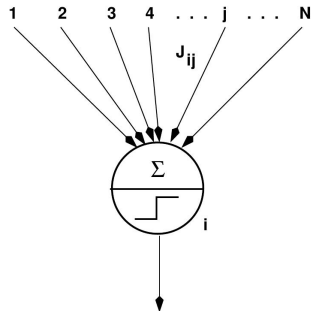
Neurons



diversity of neurons



schematic neuron



formal neuron

Human brain: $\sim 10^{11}$ neurons, each connected to $\sim 10^4$ (input & output),
 $\lesssim 5 - 6$ handshakes between any pair

What Individual Neurons Do: Linear Separation

- Neurons: two state threshold elements, **firing** or **non-firing**

$$S_i \in \{1, 0\}$$

[W. S. McCulloch, W. Pitts (1943)]

- input output relation

Post-synaptic potential:

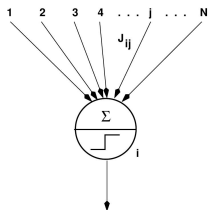
$$u_i = \sum_j J_{ij} S_j \equiv \mathbf{J}_i \cdot \mathbf{S}$$

\Rightarrow **output:**

$$S_i = \Theta(u_i - \vartheta_i)$$

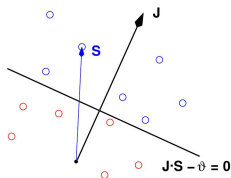
- Synaptic couplings:

$$J_{ij} \begin{cases} > 0 & ; \text{excitatory} \\ < 0 & ; \text{inhibitory} \end{cases}$$



Neuron i receives N inputs (evidence!) S_j , gives weight J_{ij} to input S_j , sums all up, and compares to threshold ϑ_i .

Fire if above, **don't fire** if below.



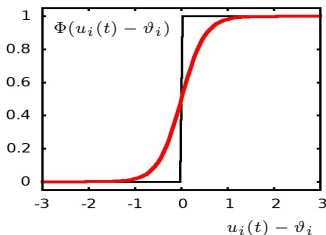
classification by linear separation

Neural Networks and Dynamics

- Neurons interacting in networks: output of a neuron is used as input by others **at later times** (important when feedback loops exist).
- **Dynamics** (can be deterministic or probabilistic):

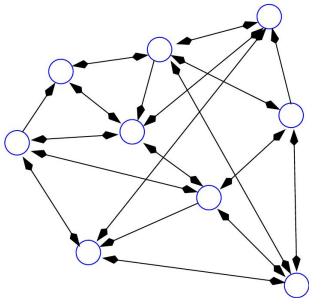
$$u_i(t) = \sum_j J_{ij} S_j(t)$$

$$\text{Prob}\{S_i(t + \Delta t) = 1\} = \Phi(u_i(t) - \vartheta_i)$$

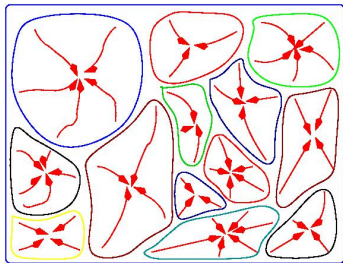


Recursive Networks – Attractors

- Deterministic dynamics: two types of global states: **transient** or **persistent**; the latter can be **stable attractors** (fixed points, limit cycles). \Rightarrow associative memory, motion control,
- Probabilistic dynamics: **fluctuations about attractors of deterministic dynamics & occasional transitions between them** (long-lived sets of states).



recursive Architecture

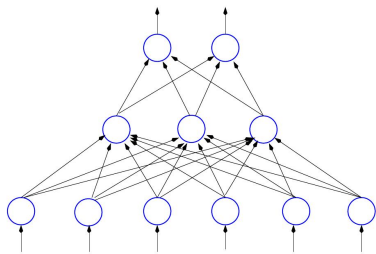


attractors, **associative memory**

attractors depend on $\{J_{ij}, \vartheta_i\}$: created by 'learning' or 'adaptation'

[D.O. Hebb (1949); J.J. Hopfield (1982)]

Feed-Forward Networks – Classification/Regression



feed-forward network
'question-answer machine'

- pattern recognition
- reading of written text
- triggers in high-energy physics
- control of autonomous vehicles
- playing the game of GO
- predicting protein structure ...
-
-
- **trained on examples & able to generalize**

Learning rules exist for systems with with smooth I/O relations.
Variants of these are the work-horses of the current AI revolution.

In human brains: **mixture of modules with recursive and feed-forward architecture.**

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Information Processing & Learning

- neural firing states \iff information
- neural dynamics \iff information processing
- synaptic couplings \iff information processing capabilities
- processing **capabilities evolve** through learning/training

- Correspondences (high level)
 - neural firing states \simeq brain states \iff cognitive states
 - neural dynamics \iff generates representations of world and acts on them; interprets, generates actions/reactions
 - synaptic couplings \iff cognitive repertoire
 - learning \iff adapt representations to improve adequacy, performance, success rate, survival probability, rewards, ...

- Note: No CPU, slow but massively parallel hardware, highly fault tolerant, no separation between hardware and software

Learning — What is Involved?

- In order to establish and stabilize a desired set of (sequences of) neural activity patterns (\simeq 'procedures') $\{S^\mu\}$, $\mu = 1, 2, \dots, p$,

$$S_i^\mu(t + \Delta t) = \Theta\left(\sum_j J_{ij} S_j^\mu(t) - \vartheta_i\right) \quad \forall i, \mu, t \quad (*)$$

\Leftrightarrow **Require:** Parameters $\{J_{ij}, \vartheta_i\}$ must be found such that for each procedure μ and at all t , every neuron i should do what it is supposed to do in that situation, given the right input.

- Procedures could be realised as
 - fixed point attractors (**associative memory**)
 - firing sequences (**motion control**)
 - limit cycles (**biological clocks**)
 - input-output pairs (**classifications of sensory data**)
 - ...

Learning — When and Why Can it Fail?

- Recall: We want $\{J_{ij}\}$ and $\{\vartheta_i\}$ such that the network dynamics correctly implements all procedures S^μ , $\mu = 1, \dots, p$.
- Analyse learning in terms of **version space**:

$$V_p = \left\{ J_{ij}, \vartheta_i; \text{ compatible with } S^\mu \text{ for all } \mu = 1, \dots, p \right\}$$

- Key point** to note:
 - Every new pattern/procedure puts **new constraints** on $\{J_{ij}, \vartheta_i\}$.
 - \Rightarrow version space shrinks

$$V_0 \supseteq V_1 \supseteq V_2 \supseteq V_3 \supseteq \dots$$

- For given architecture/structure, there may exist

$$p_{\max} \quad \text{s.t.} \quad V_p = \emptyset \quad \text{for } p > p_{\max}$$

independently of learning algorithm/strategy.

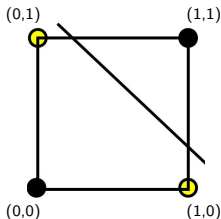
[E. Gardner (1988)]

Learning — When and Why Can it Fail?

- p_{\max} depends on architecture and (statistical) properties of $\{S^\mu\}$. Typically of the order of the number N of input channels (adaptable parameters) per neuron.
- Architectures/structures have restrictions on the problems they **can** represent/solve. E.g.

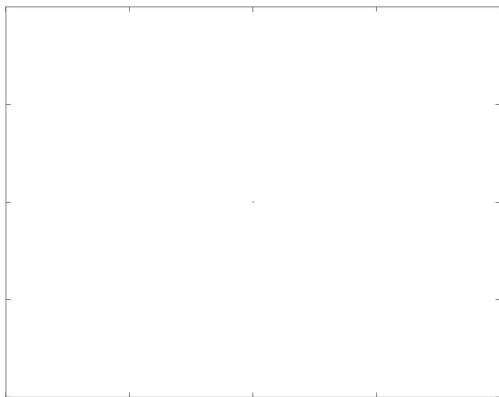
$$S_0 = \text{XOR}(S_1, S_2) \neq \Theta(J_{01}S_1 + J_{02}S_2 - \vartheta_0)$$

for **any** $J_{01}, J_{02}, \vartheta_0$.



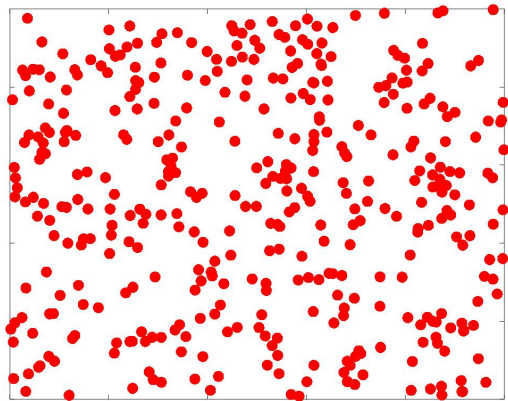
- As $p \rightarrow p_{\max}$ for given problem class, the version space can become **fragmented** (disconnected). Finding solutions that accommodate new patterns can become difficult (even impossible without violating some constraints 'on the way' to the new solution).

Learning — When and Why Can it Fail?



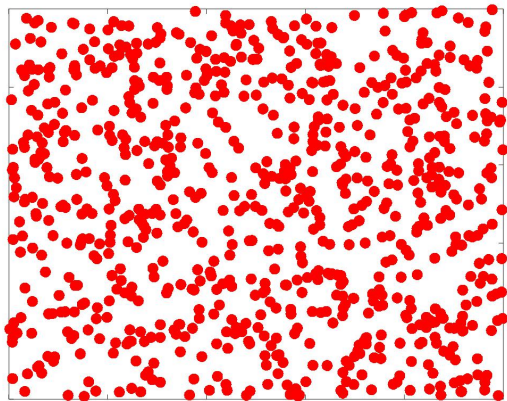
Version space: shrinking and fragmentation

Learning — When and Why Can it Fail?



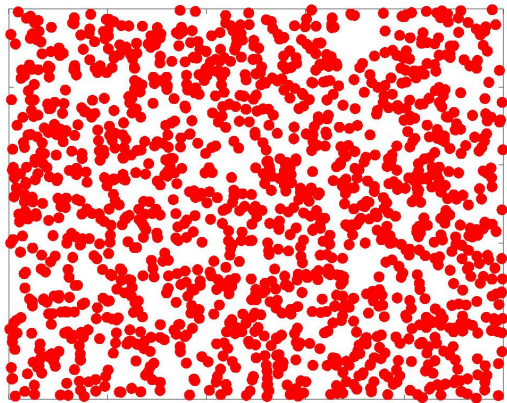
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Learning — When and Why Can it Fail?



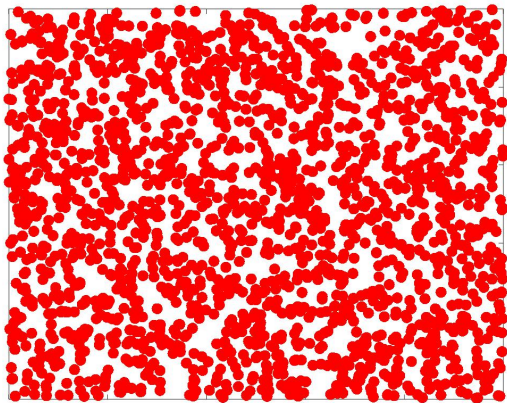
Version space: shrinking and fragmentation

Learning — When and Why Can it Fail?



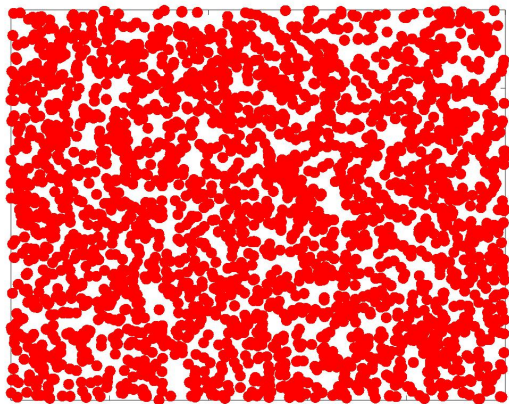
Version space: shrinking and fragmentation

Learning — When and Why Can it Fail?



Version space: shrinking and fragmentation

Learning — When and Why Can it Fail?



Version space: shrinking and fragmentation

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Learning Systems — From Societies of Brains . . .

- **Any** complex system able to generate representations of the world is an information processing system.
- Need not be an individual agent, but could be **a swarm, a team, an organization, or a society of complex agents**.
- Information exchange in societies via language, actions, gestures, . . .
- ⇒ **Collective information processing**, if exchanged information influences/constrains (re-)action on receiving side.
- **Any** such system is **capable of learning**, if interactions (evaluations of exchanged information) are adapted, e.g. in order to improve performance, utility functions, . . .

- Recall that this is essentially the mechanism underlying learning in brains!

... to Brains of Societies?

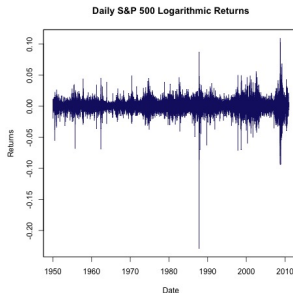
- Collective information processing in groups, communities, organizations, or societies will be guided by attractors.
 - subsets of system states or sequences of system state generated and reinforced by dynamics at the system level (autopoiesis)
 - pattern formation on short time-scales, (e.g. panics, emergence of rhythmic clapping after concert performances, . . .)
 - on longer time-scales: fashions, conventions , adoption of new technologies, . . . , trends in art and science, dominant scientific paradigms, moral value-systems).
- **Recall:** multiplicity/diversity of attractors in systems with **given** interactions; may observe occasional transitions between different attractors (spontaneous, or triggered by events)
- An attractor a system finds itself in may be contingent on past events. Degree of rigidity/fluidity of a society is a collective phenomenon (**susceptibility**).
- Important role of media of/technology for information exchange (reach, timescales . . .) [M McLuhan 1960s: Media as extensions of our senses . . .]

... to Brains of Societies?



Murmuration of starlings

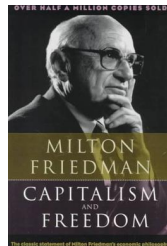
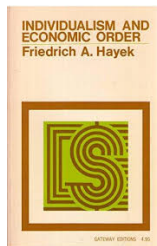
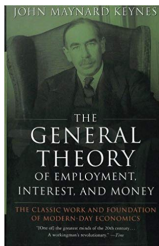
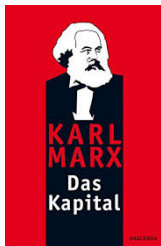
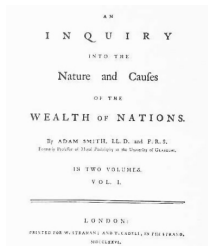
... to Brains of Societies?



Dynamics of Financial Markets:

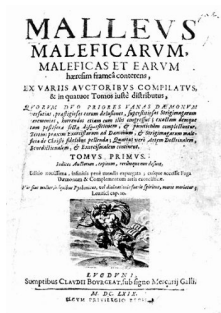
- (i) Fat tailed (leptokurtic) distributions of returns (student's t);
 - (ii) Fast decay of correlations of returns;
 - (iii) Very slow decay of correlations of volatilities (volatility clustering);
- universal across virtually all markets.**

... to Brains of Societies?



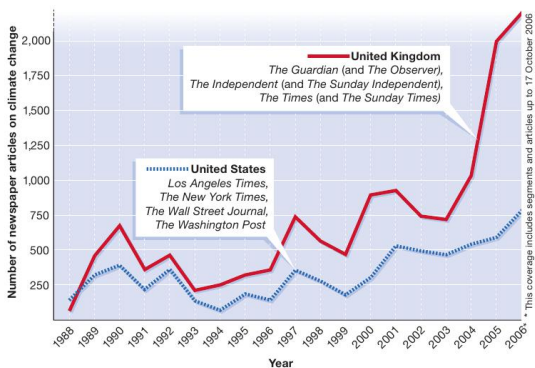
Evolution and Influence of Economic Theory

... to Brains of Societies?



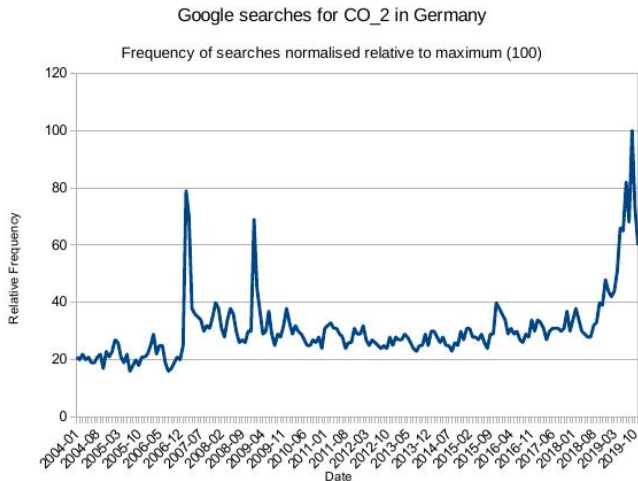
Witch trials in the early modern period
Estimated 40,000 – 60,000 victims, 80% of which women
(Heinrich Kramer: Der Hexenhammer (1484))

Brains of Societies — Press Coverage & Public Debate



[T Boykoff & S R Rajan, EMBO Report 7 207-211 (2007)]

Brains of Societies — Public Awareness



Public awareness: Google Searches for CO₂ in Germany; data from GOOGLE TRENDS. Peak in 2007 related to G8

Heiligendamm Summit (sustainability prominently on agenda for first time including (nonbinding) agreement aiming to at least halve CO₂ emissions by 2050); peak in 2009 combined effect G8 L'Aquila Summit and Copenhagen Summit on Climate Change

Brains of Societies — Collective Attention

- Results of Google search: **barely looked at beyond page 5.**
- Documents on page 1 **“in the light of collective attention”**
- Result of interaction between
 - page-rank: \Leftrightarrow number (& importance!) of incoming links \simeq votes
 - user behaviour: # of visits to a page ...
 - ... **which are in turn influenced by page rank!**
 \implies recursive dynamics with attractors!



Internet [opte.org (2007)]

- Some details at: <http://en.wikipedia.org/wiki/PageRank>
- Similar mechanisms at work in the domain of citation counts in science

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What About Limitations?

- Explore whether the hypothesis about existence of fundamental limitations of representability in organizations survives scrutiny.
- Do this via series of approximations.
 - Start with society of two-state (yes/no) agents. Want:¹

$$u_i^\mu = \sum_j J_{ij} S_j^\mu, \quad S_i^\mu = \Theta(u_i^\mu - \vartheta_i) \quad \forall i, \mu \quad (*)$$

⇔ **Require:** Parameters $\{J_{ij}, \vartheta_i\}$ must be found such that an input $\mathbf{S} = (S_j)$ to agent i which represents 'context' μ , must generate the output of agent i that is required in context μ .

- Standard theory for Mc Culloch-Pitts neurons applies. Typically $p_{\max} = \mathcal{O}(N)$. Precise values are known and depend on statistics; e.g. $p_{\max} = 2N$ for unbiased random patterns. [E. Gardner (1988)]

¹Without loss of generality, choose procedures to consist of single I/O pairs

- **First critique:** states of agents are not binary

- **Answer:** assume $S_i \in \mathbb{R}$ and graded response dynamics. Want

$$u_i^\mu = \sum_j J_{ij} S_j^\mu, \quad S_i^\mu = g_i(u_i^\mu - \vartheta_i) \quad \forall i, \mu \quad (*)$$

for some (continuous) response functions g_i .

- Embedding routines (with tolerance ε):

⇔ **Require:** Parameters $\{J_{ij}, \vartheta_i\}$ must be found such that an input $S = (S_j)$ to agent i sufficiently close to 'context' μ , must generate an output of agent i sufficiently close to what is required in context μ .

- Adapt standard theory to generalize to graded response neurons. Typically $p_{\max} = \mathcal{O}(N)$. Precise values are known and depend on statistics, input/output tolerance ε and the shape of the transfer-functions g_i . [D. Bollé, RK, J. van Mourik (1993)]

- **Second critique:** state variables communicated between agents are not simple scalars (language, gestures, actions, ...).

- **Answer:** enlarge dimension. $\mathbf{u}_i = (u_i^a) \in \mathbb{R}^K$.

$$u_i^{\mu a} = \sum_{jb} J_{ij}^{ab} S_j^{\mu b} \quad , \quad S_i^{\mu a} = g_i^a(u_i^{\mu a} - \vartheta_i^a) \quad \forall i, \mu \quad (*)$$

- Embedding patterns with tolerance ε then requires multidimensional generalization of previous argument.

⇔ **Require:** Parameters $\{J_{ij}^{ab}, \vartheta_i^a\}$ must be found such that an input $\mathbf{S} = (S_j^a)$ to agent i sufficiently close to 'context' μ , must generate an output of agent i sufficiently close *in all its dimensions* to what is required in context μ .

- Same conclusions, although computations have not been done.
Expect $p_{\max} = \mathcal{O}(KN)$

- **Third critique:** Agents are complex and have internal adaptable structure to 'compute' outputs.

- **Answer:** could take internal adaptable structure into account

$$g_i^a(\mathbf{u}_i(t)) = g_{\mathbf{w}_i}^a(\mathbf{u}_i(t))$$

in which \mathbf{w}_i stands for the collection of adaptable parameters within a function-class representable by agent i .

⇔ **Require:** Parameters $\{J_{ij}^{ab}, \mathbf{w}_i\}$ must be found such that an input $\mathbf{S} = (S_j^a)$ to agent i sufficiently close to 'context' μ , must generate an output of agent i sufficiently close *in all its dimensions* to what is required in context μ .

- Conclusion about existence of fundamental limitations are not altered, if internal parameters are taken into account. Get further enlargement of expected p_{\max} .
- Only partial results known. If g_i^a represents the computation of a feed-forward neural network with M hidden nodes, get an extra factor $\mathcal{O}(\ln M)$ for random binary patterns. [E. Baum, D. Haussler (1989)]

- **Fourth critique:** Individuals are not machines (but autonomous & unpredictable).
- **Answer:** A difficult one. A tentative answer, as far as the question of existence of fundamental limitations is concerned:
 - Could model unpredictability and autonomy by replacing the g_i^a by **random functions** which produce a range of outputs **with a statistics constrained by the inputs**.

⇔ **Require:** Parameters $\{J_{ij}^{ab}, \mathbf{w}_i\}$ must be found such that an input $\mathbf{S} = (S_j^a)$ to agent i close to 'context' μ , should *in all its dimensions and with sufficiently high probability* generate an output sufficiently close to what is required of agent i in context μ .

- If this were not guaranteed for a procedure μ , there would be too many malfunctioning agents, which would prevent the reliable execution of that 'collective procedure'.
- Conclusion about existence of fundamental limitations not altered. Details would depend of specification of probabilistic constraints.

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Wrapping Up

- Note that collective information processing and learning is ubiquitous; **it doesn't begin and it doesn't stop at the individual (neuron) level.**
- Note hierarchy of levels: neurons → cortical columns → brain organization (visual, somatosensory, auditory, olfactory ... cortices, cerebellum ...) → brain → society of brains.
- Note that information exchange and processing between levels happens both ways: 'up and down'.
- Note that **learning** occurs at any level where evaluations of exchanged information are adapted, e.g. in order to improve performance.

Insights

- **Collective information processing in groups, communities, organizations, or societies will be guided by attractors.**
 - pattern formation on various time-scales, e.g.
 - swarming patterns, panics, emergence of rhythmic clapping
 - fashions, dynamics of economic cycles, adoption of new technologies
 - dominant paradigms or trends in art and science, moral value-systems
- **Fundamental limitations are likely to exist** for learning (i.e. the attainable cognitive repertoire in a given architecture) at all levels, including at the level of groups, organizations and societies.
 - slow-down of dynamics of change in complex organizations and highly evolved societies (fragmentation of version spaces)
 - some of the major transformations in history may be understood as finding 'extra dimensions' to accommodate solutions to problems previously unsolvable, given the structure (eg. hunter/gatherer to agricultural transition, division of labour & specialization, formation of states, invention of writing, printing with moveable letters, computers, the world wide web ...)

Lessons?

- Note: **Dialectics** of innovation:
 - (i) Version space **expands**, because existing procedures are made obsolete (\Rightarrow constraints on parameters no longer required).
 - (ii) Version space **shrinks**, because new procedures need to be implemented.
- Policy making or managing organizations should ideally ensure that balance is always on the right side!
 - For Innovations that don't produce additional problem solving capabilities, **the effect of (i) must always be dominant.**
 - Conversely, the **only justification for dominance of effect (ii)** is indeed an **enrichment of the repertoire of information processing capabilities** of an organization.
- Vehicles for enhancing collective cognitive repertoire: arts, sciences, collaboration, inclusion, participation, interdisciplinarity

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Summary

- Neural information processing as paradigm for decentralized & collective information processing
- Hierarchy of levels of information processing & meanings
- Structure and limits of representability (version spaces)
- Society of brains as information processing systems
- Framework to rationalize pattern formation in societies on many time-scales
- Limits on learning adaptability and functionality for such systems
- Lessons for policy making

Thank you!