

Properties of the Lorentz Group.

$$\Lambda^T \cdot \eta \cdot \Lambda = \eta \Rightarrow \det(\Lambda) = \pm 1.$$

and as $\eta_{00} = +1$ then $\Lambda^\mu_{0} \eta_{\mu\nu} \Lambda^\nu_{0} = +1.$

$$\Rightarrow \Lambda^0_{0} \eta_{00} \Lambda^0_{0} = +1.$$

$$\therefore (\Lambda^0_{0})^2 = +1.$$

- The proper Lorentz group has $\det(\Lambda) = +1 \Rightarrow \Lambda \in SO(1,3)$.
- The orthochronous group has $(\Lambda^0_{0}) \geq 1$.

- $O(3)$ is a subgroup of $O(1,3)$ i.e. $\Lambda = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & & & \\ 0 & & R & \\ 0 & & & \end{pmatrix}$ with $R \in O(3)$.

- In addition to ordinary rotations and reflections, we have "pure" Lorentz boosts: e.g.

$$\Lambda = \begin{pmatrix} \cosh(\xi) & -\sinh(\xi) & 0 & 0 \\ -\sinh(\xi) & \cosh(\xi) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

This indicates an x-direction boost, but equivalently there are boosts in the y and z directions.

(N.B. when a boost is combined with a rotation it is sometimes referred to as a boost too but the "pure" is dropped.)

- The proper orthochronous Lorentz group is generated completely by rotations and pure Lorentz boosts.

N.B. As there are 3 pure boosts and 3 independent rotations

$SO(1,3)$ is generated by 6 continuous real parameters.

One can also see it has a basis of skew-symmetric matrices
 $\Rightarrow$ 6 parameters.

The proper Lorentz group and $SL(2, \mathbb{C})$.

Recall the Pauli matrices (and the identity):

$$\sigma_0 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad \sigma_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_2 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

Now consider for each Lorentz vector x^μ the 2×2 matrix:

$$X \equiv x^\mu \sigma_\mu.$$

Now $[\sigma_i, \sigma_j] = 2i\epsilon_{ijk}\sigma_k$ and in fact $\sigma_i \sigma_j = \begin{cases} i\epsilon_{ijk}\sigma_k & i \neq j \\ \delta_{ij}\sigma_0 & i = j \end{cases}$.

And $X \sigma_\nu \equiv x^\mu \sigma_\mu \sigma_\nu = x^\mu \begin{cases} i\epsilon_{ijk}\sigma_k \\ \text{or } x^\mu \delta_{\mu\nu} \sigma_0 \end{cases}$.

So as $\text{Tr}(\sigma_1) = \text{Tr}(\sigma_2) = \text{Tr}(\sigma_3) = 0$ and $\text{Tr}(\sigma_0) = 2$.

$$\text{Tr}(X \sigma_\nu) = x_\nu \text{Tr}(\sigma_0) = 2x_\nu.$$

$$\therefore x_\nu = \frac{1}{2} \text{Tr}(X \sigma_\nu).$$

$$\text{Now } \bar{X} \equiv x^\mu \sigma_\mu = \begin{pmatrix} x^0 - x^3 & -x^1 + ix^2 \\ -x^1 - ix^2 & x^0 + x^3 \end{pmatrix}.$$

So that $\det(X) = (x^0)^2 - (x^3)^2 - (x^1)^2 - (x^2)^2 = x^\mu x_\mu$.

$\therefore$ Transformations on X of the form:

$$A X A^\dagger = X'$$

Which preserve $\det(X) = X^2 = \det(X')$ represent a

Lorentz transformation of x^μ . The condition on A is:

$$\det(A) = \det(A^\dagger) = 1.$$

Hence $A \in SL(2, \mathbb{C})$ encodes a proper Lorentz transformation on x^μ .

Generators of $SO(3,1)$

Using $-iX = \frac{d\Lambda}{d\theta} \Big|_{\theta=0}$.

We have the rotation generators:

$$-iX_1 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \end{pmatrix}, \quad -iX_2 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}, \quad -iX_3 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

And the pure Lorentz boosts:

$$-iB_1 = \begin{pmatrix} 0 & -1 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad -iB_2 = \begin{pmatrix} 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \quad -iB_3 = \begin{pmatrix} 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 \end{pmatrix}.$$

Now $[B_1, X_1] = 0$.

$$[B_1, X_2] = iB_3$$

$$[B_1, B_2] = -iX_3 \quad \text{etc.}$$

Giving: $[X_i, X_j] = i\epsilon_{ijk} X_k$,

$$[X_i, B_j] = i\epsilon_{ijk} B_k,$$

$$[B_i, B_j] = -i\epsilon_{ijk} X_k.$$

If one uses the combinations:

$$X_i^\pm \equiv \frac{1}{2}(X_i \pm iY_i) \quad i = 1, 2, 3.$$

Then the commutation relations simplify:

$$[X_i^+, X_j^+] = i\epsilon_{ijk} X_k^+ \quad su(2)$$

$$[X_i^-, X_j^-] = i\epsilon_{ijk} X_k^- \quad su(2).$$

$$[X_i^+, X_j^-] = 0.$$

This gives two copies of the $SU(2)$ algebra commutators.
 $so(1,3) \otimes \mathbb{C} \cong SU(2) \oplus SU(2)$.

However locally $SO(1,3)$ is isomorphic to $SL(2, \mathbb{C})$

in fact the proper orthochronous Lorentz group is isomorphic to $SL(2, \mathbb{C}) / \mathbb{Z}_2$ (cf. $SO(3) \cong SU(2) / \mathbb{Z}_2$)

and $SL(2, \mathbb{C})$ is the complexification of $SU(2)$.

One can label the representations of $SO(1,3)$ by the dimensions, or "spins", of the two $SU(2)$ irreps.

The Poincaré Group.

The Poincaré group consists of the Lorentz transformations and additionally translations:

$$P \equiv \{ (\Lambda, a) \mid \Lambda \in \text{Lorentz group}, a \in \mathbb{R}^4 \}.$$

A general transformation of the Poincaré group takes the form:

$$x'^{\mu} = \Lambda^{\mu}_{\nu} x^{\nu} + a^{\mu}.$$

Representations of the Lorentz Group and Lorentz Tensors.

- The trivial representation (objects which are invariant under the Lorentz transformations) such objects in the vector space of the representation are called Lorentz scalars.
- The standard representation on $\mathbb{R}^4$ (define it to be $\pi^{(1,0)}$)

acts as: $x^{\mu} \xrightarrow{\Lambda} x'^{\mu} = \Lambda^{\mu}_{\nu} x^{\nu}$.

x^{ν} is a rank $(1,0)$ tensor component, also called contravariant.

- The contragredient representation acting on tensors with components x_μ :

$$x_\mu \rightarrow x'_\nu = \Lambda^\mu_\nu x_\mu.$$

x_μ are called co-vectors, or rank(0,1) tensors.

- In fact $\pi^{(0,1)}$ and $\pi^{(1,0)}$ are equivalent with the intertwiner map being η :

$$\text{if } \pi^{(1,0)}(\theta) = \Lambda \quad \text{and} \quad \pi^{(0,1)}(\theta) \equiv (\pi^{(1,0)}(\theta^{-1}))^T$$

$$\text{then as } \Lambda^{-1} = \eta \cdot \Lambda^T \cdot \eta$$

$$\Rightarrow (\pi^{(0,1)}(\theta))^T = \eta \cdot (\pi^{(1,0)}(\theta))^T \cdot \eta^{-1}$$

$$\Rightarrow \pi^{(0,1)}\theta \equiv \eta \cdot \pi^{(1,0)}(\theta) \cdot \eta^{-1}.$$

- General tensor representations are built from products of the vector and co-vector representations and called (r,s) -tensors:

$$\underbrace{\pi^{(1,0)} \otimes \pi^{(1,0)} \otimes \dots \otimes \pi^{(1,0)}}_r \otimes \underbrace{\pi^{(0,1)} \otimes \dots \otimes \pi^{(0,1)}}_s.$$

(r,s) -tensors have components $T^{M_1 \dots M_r}_{V_1 \dots V_s}$.

And under a Lorentz transformation we have:

$$T^{M_1 \dots M_r}_{V_1 \dots V_s} \xrightarrow{\Lambda} T'^{M_1 \dots M_r}_{V_1 \dots V_s} = \Lambda^{M_1}_{K_1} \dots \Lambda^{M_r}_{K_r} \cdot \Lambda^{J_1}_{V_1} \dots \Lambda^{J_s}_{V_s} T^{K_1 \dots K_r}_{J_1 \dots J_s}.$$

- $\eta_{\mu\nu}$ still acts to raise and lower indices:

$$\eta_{\mu,g} T^{M_1 \dots M_r}_{V_1 \dots V_s} = T^{M_2 \dots M_r}_{g, V_1 \dots V_s}.$$

- One can contract indices on an (r, s) tensor to obtain an $(r-1, s-1)$ tensor:

$$\eta_{\mu_r}^{\nu_s} T^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} = T^{\mu_1 \dots \mu_{r-1}}_{\nu_1 \dots \nu_{s-1}}$$

- One may be interested in special subsets of tensors:
- Tensors with symmetric indices (e.g. consider an $(r, 0)$ tensor):

$$T(\mu_1 \dots \mu_r) \equiv \frac{1}{r!} \sum_{\pi \in S_r} T^{\mu_{\pi(1)} \mu_{\pi(2)} \dots \mu_{\pi(r)}}$$

this is totally symmetric under the interchange of any two indices.

- Anti-symmetric tensors:

$$T[\mu_1 \dots \mu_r] \equiv \frac{1}{r!} \sum_{\pi \in S_r} \text{Sign}(\pi) T^{\mu_{\pi(1)} \dots \mu_{\pi(r)}}$$

This picks up a minus sign under the interchange of any two indices.

Example ($r=2$).

$$T(\mu\nu) \equiv \frac{1}{2} (T^{\mu\nu} + T^{\nu\mu})$$

$$\therefore T(\mu\nu) = T(\nu\mu)$$

$$T[\mu\nu] \equiv \frac{1}{2} (T^{\mu\nu} - T^{\nu\mu})$$

$$\therefore T[\mu\nu] = -T[\nu\mu]$$

$$\text{N.B. } T(\mu\nu) + T[\mu\nu] = T^{\mu\nu}$$

Symmetric part.

Antisymmetric part.

- Just as for $SO(3)$ we also have $\frac{1}{2}$ ^{odd} integer representations

$\pi^{(1/2, 0)}$ and $\pi^{(0, 1/2)}$ these are the spinor representations of the Lorentz group.