Faster Pattern Matching under Edit Distance

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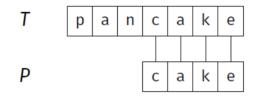
Denver, USA

Pattern Matching

Given a text T and a pattern P, compute the occurrences of P in T.

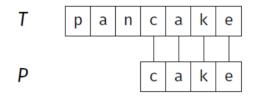
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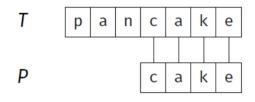


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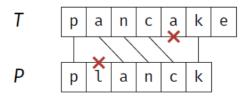
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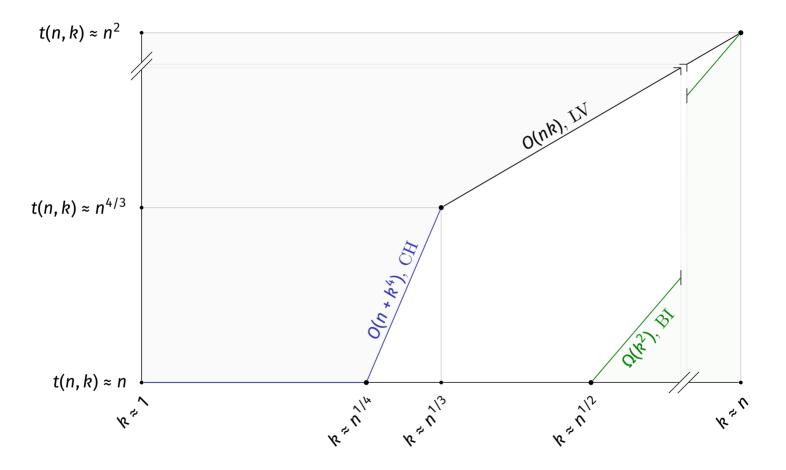
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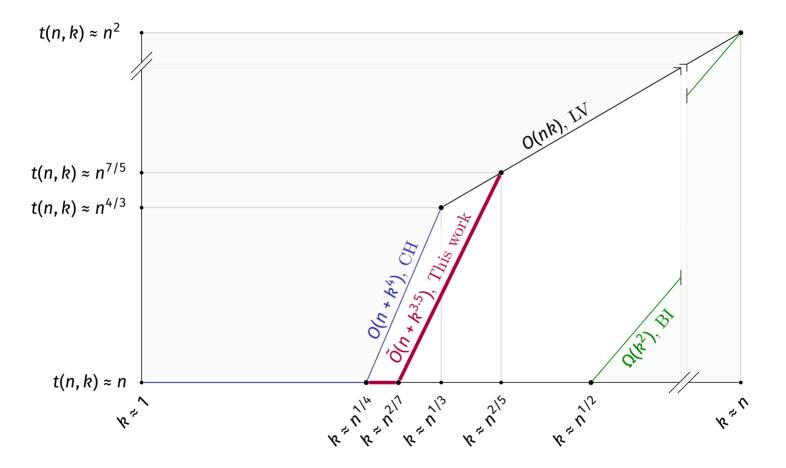
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$\Omega(k^2)$ [Backurs, Indyk; SICOMP 2018]





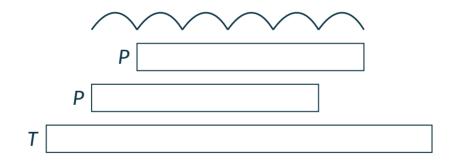


Fact [folklore] Given a pattern *P* of length *m* and a text *T* of length $n \leq \frac{3}{2}m$ at least one of the following holds:

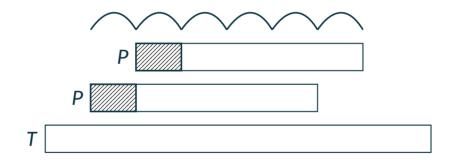
• The pattern *P* has at most one occurrence in *T*.



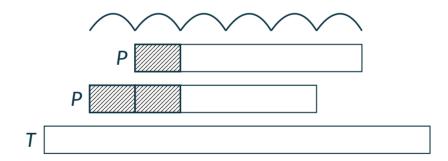
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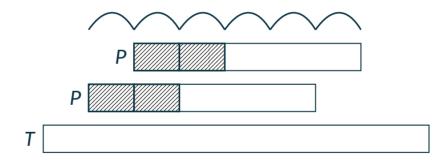
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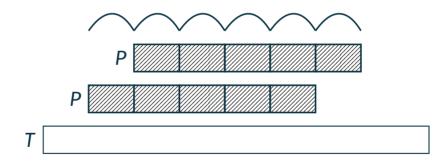
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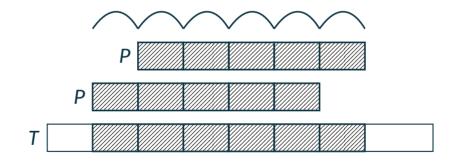


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The fragment of T spanned by P's occurrences is periodic as well.

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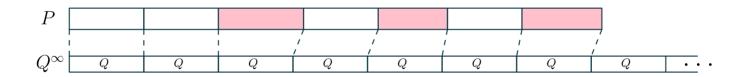
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We call this a tile decomposition of *P* with respect to *Q*.

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Reduction [CKW'20]: An algorithm that solves the almost periodic case in $\tilde{O}(k^a \cdot n/m)$ PILLAR-time, for $a \geq 3$, implies an algorithm that solves the general case in $\tilde{O}(k^a \cdot n/m)$ PILLAR-time.

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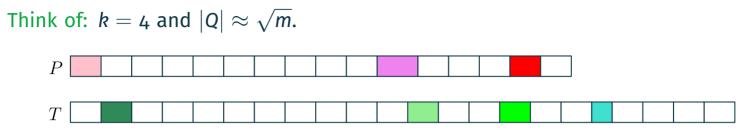
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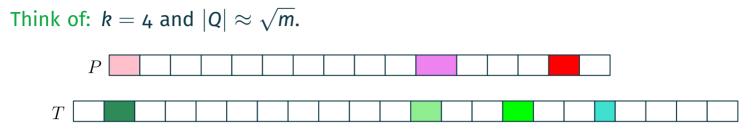
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After $\tilde{\mathcal{O}}(k^3)$ -time preprocessing, updates and queries take $\tilde{\mathcal{O}}(k)$ time.

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Each string has $\mathcal{O}(k)$ special tiles.

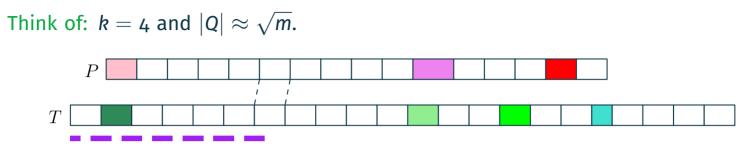






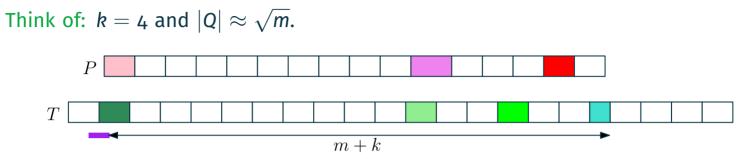
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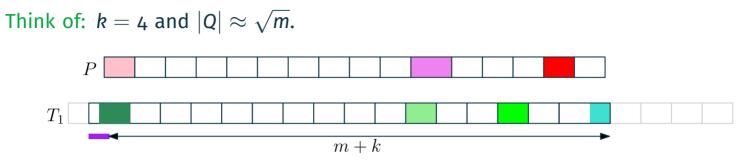
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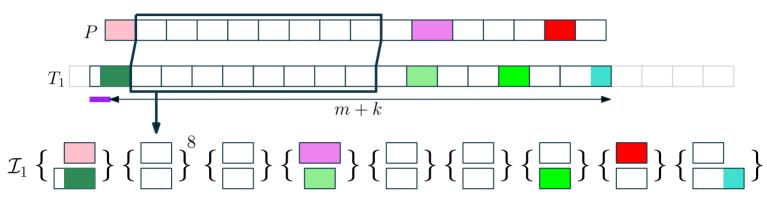
Starting positions of k-error occs in T are within $\mathcal{O}(k)$ from endpoints of tiles.

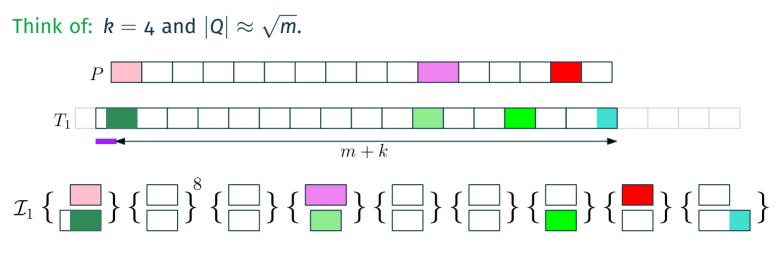




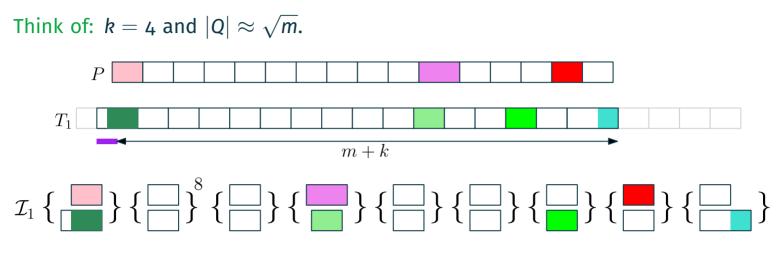
 $|T_j| = m + \mathcal{O}(k)$





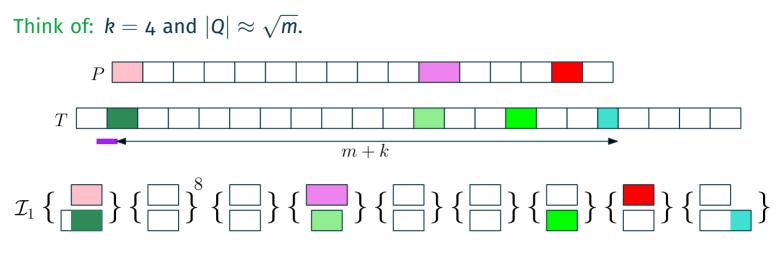


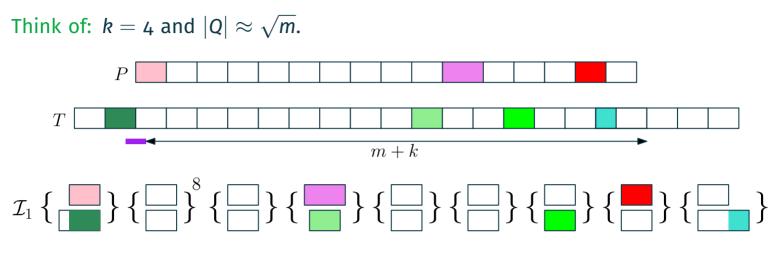
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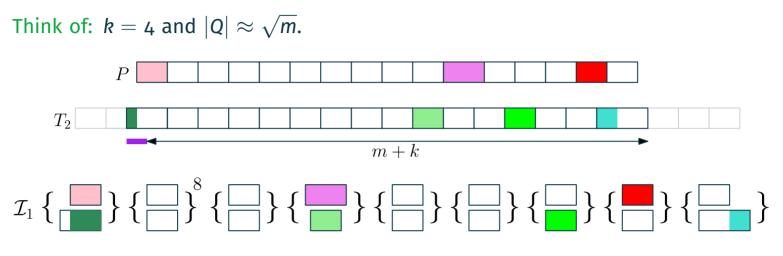


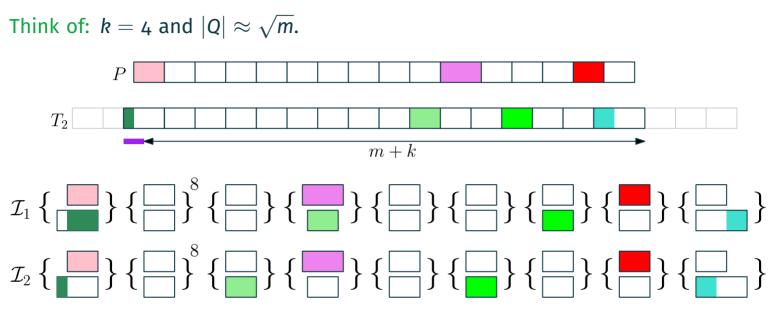
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(The leading and trailing pairs are treated separately.)

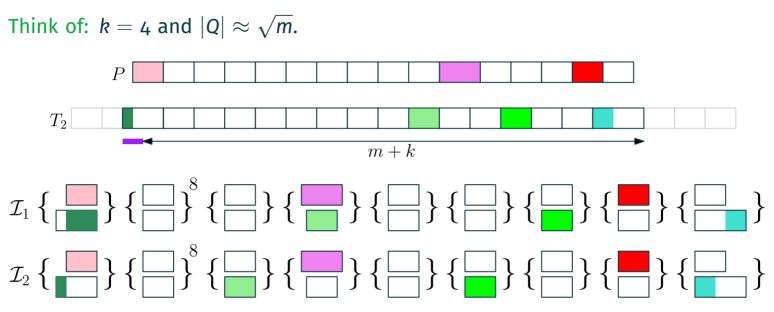




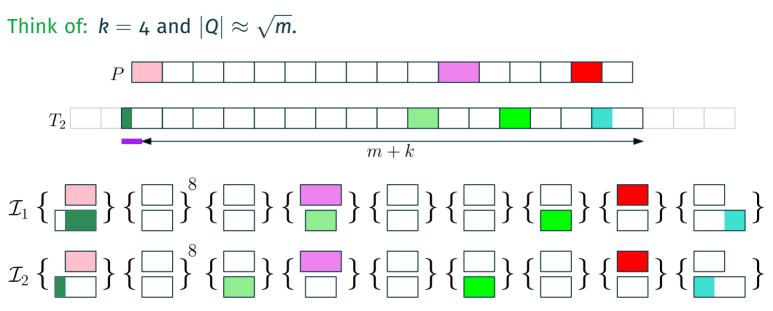




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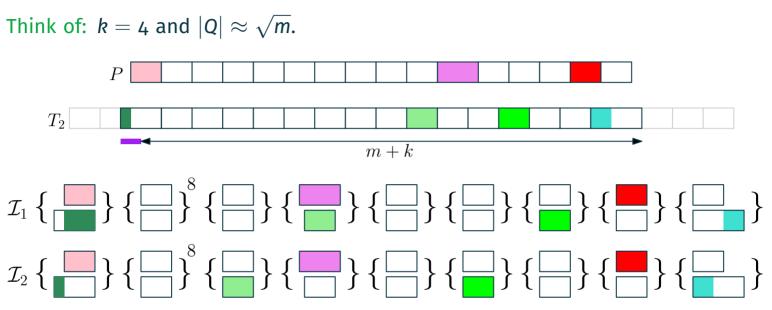


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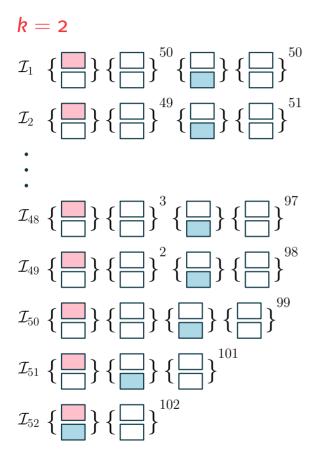


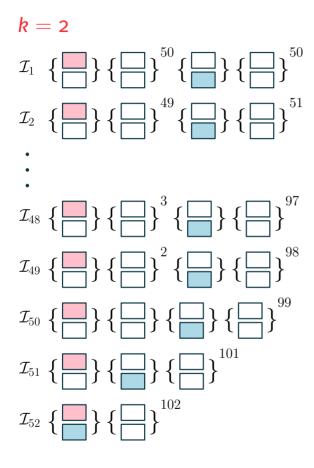
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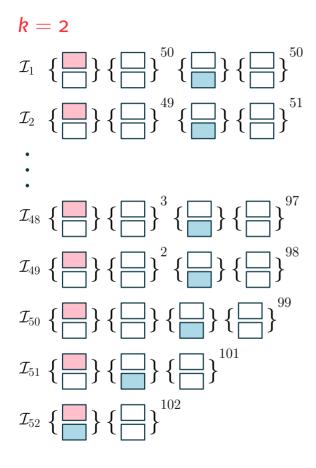
Yields
$$\tilde{\mathcal{O}}(k^3 + \sqrt{m} \cdot k^2)$$
.

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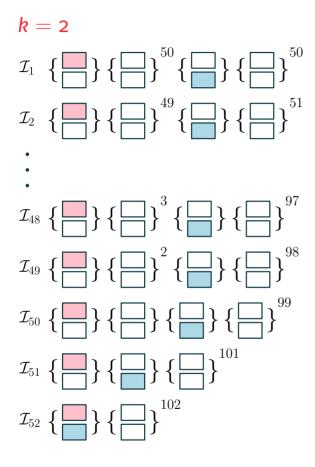


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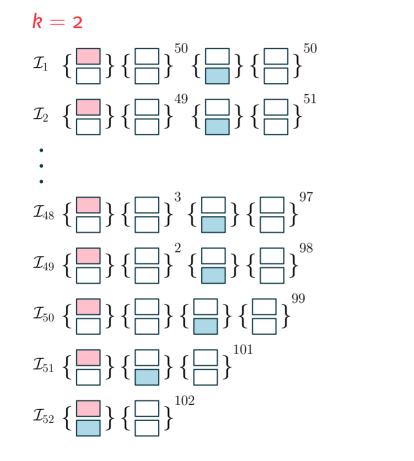
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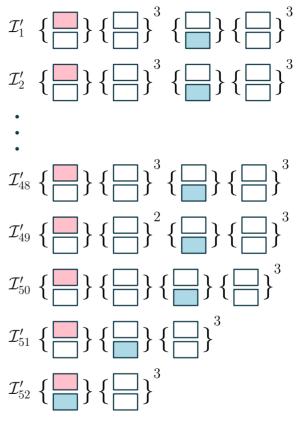


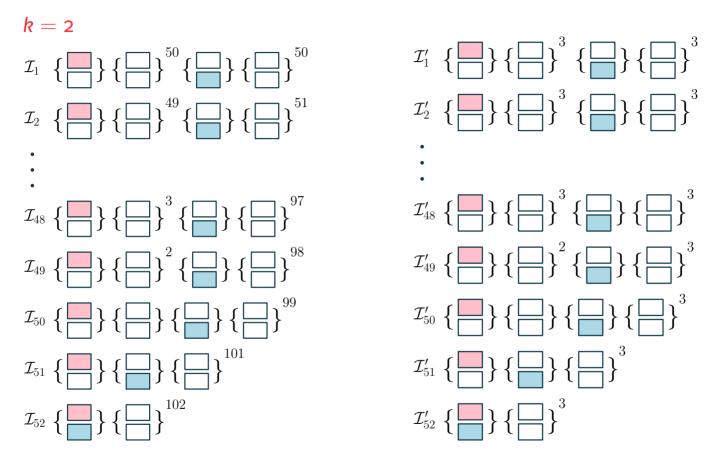
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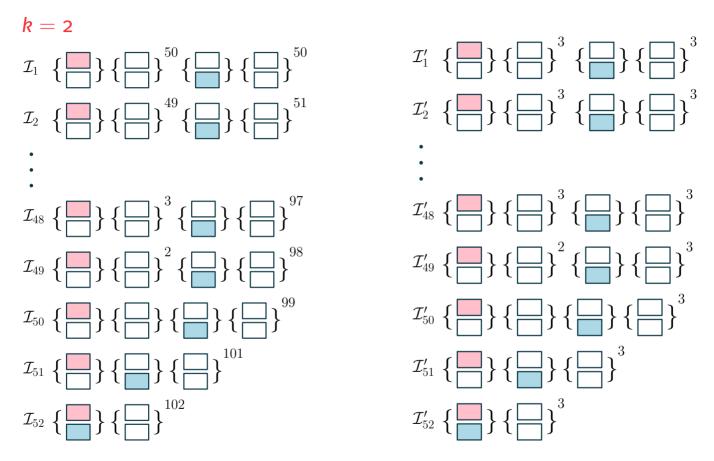
We do not lose or gain any k-error occs.







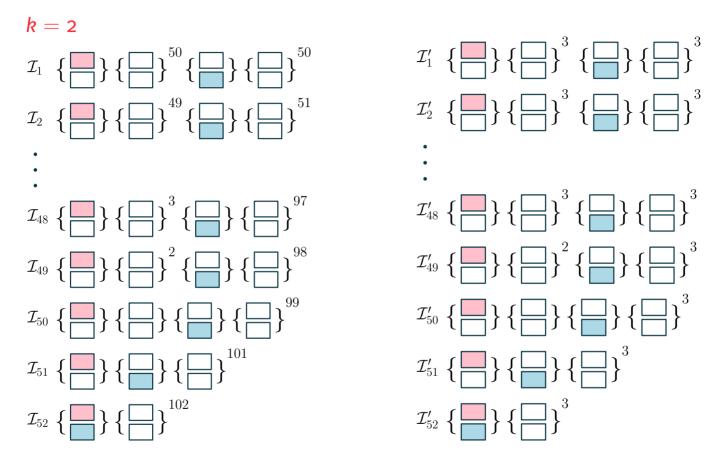
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Alternative $\tilde{\mathcal{O}}(k^4)$ -time algorithm!

Faster Pattern Matching under Edit Distance

Overview for $\mathcal{O}(k^{2.5})$ DPM-updates

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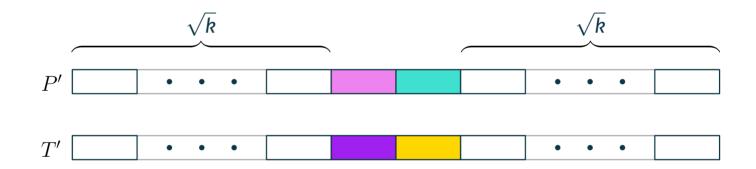
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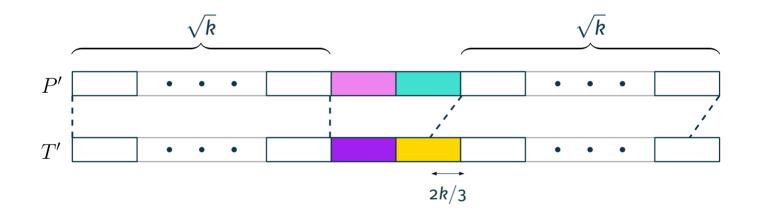
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Cost:
$$O + O + \sqrt{k} \cdot \delta_E(Q, rot^{2k/3}(Q))$$
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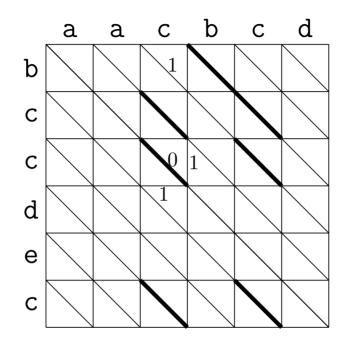
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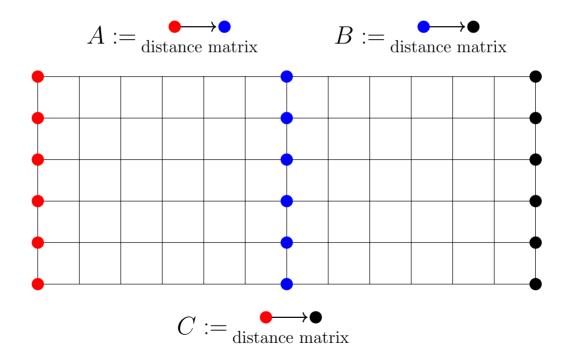
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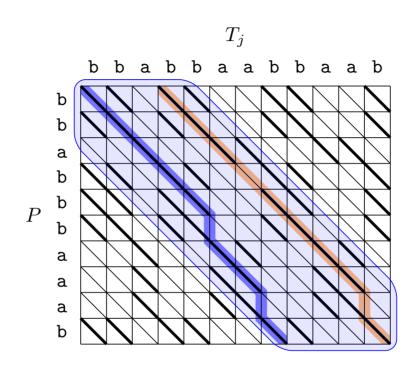
This yields $\mathcal{O}(k^{2.5})$ DPM-updates and hence $\tilde{\mathcal{O}}(k^{3.5})$ time overall.



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Theorem [Tiskin; Algorithmica 2015] Matrix *C* can be computed from (small representations of) $n \times n$ matrices *A* and *B* in $\mathcal{O}(n \log n)$ time.



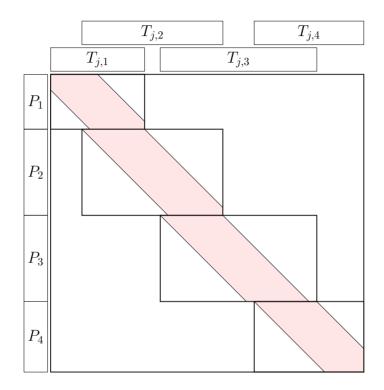


 $P = 10, T_j = 12, k = 2.$

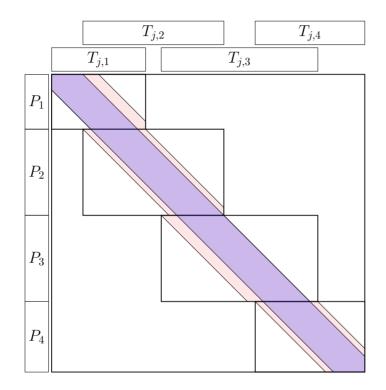
Only $|T_j| - |P| + 2k + 1 = O(k)$ diagonals are relevant.

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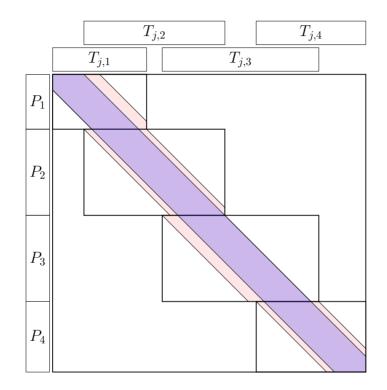
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What if we allow for some approximation by also reporting an arbitrary subset of the positions in $\operatorname{Occ}_{(1+\epsilon)k}^{E}(P,T) \setminus \operatorname{Occ}_{k}^{E}(P,T)$ for a small $\epsilon > 0$?

What is the right exponent?

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We report starting positions. How fast can we report substrings?

The End

Thank you for your attention!

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