

Continuous Verification of Machine Learning a Declarative Programming Approach

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Lab for AI and Verification, Heriot-Watt University, Scotland

Invited talk at PPDP 2020













Why Verifying Neural Networks?





Why Verifying Neural Networks?

Challenges of Neural Network Verification





Why Verifying Neural Networks?

Challenges of Neural Network Verification

Continuous Verification



Why Verifying Neural Networks?

Challenges of Neural Network Verification

Continuous Verification



Autonomous cars





Autonomous cars



Smart Homes





Autonomous cars



Robotics



Smart Homes



Autonomous cars



Robotics



Smart Homes



Chat Bots







...and many more ...

AI is in urgent need of verification: safety, security, robustness to changing conditions and adversarial attacks, ...

Lab for AI and Verification

- ▶ LAIV launched in March 2019
- ...in order to accumulate local expertise in AI, programming languages, verification
- ... and respond to demand in Edinburgh Robotarium and Edinburgh Center for Robotics





LAIV members:





























Perception and Reasoning

AI methods divide into:



Perception and Reasoning

AI methods divide into:

Perception tasks:

Computer Vision







Perception and Reasoning

AI methods divide into:

Perception tasks:





A.Hill, E.K. and R.Petrick: Proof-Carrying Plans: a Resource Logic for AI Planning. PPDP'20.



Neural Networks...





take care of **perception** tasks:

...

computer vision speech recognition pattern recognition

Neural Networks...



take care of **perception** tasks:

...

computer vision speech recognition pattern recognition

In:

. . .

autonomous cars robots medical applications chatbots mobile phone apps





Why Verifying Neural Networks?

Challenges of Neural Network Verification

Continuous Verification



... a function

 $N: \mathbb{R}^n \to \mathbb{R}^m$

... a function that separate inputs (data points) into classes



... a function that separate inputs (data points) into classes

Suppose we have four data points

	x_1	x_2	у
1	1	1	1
2	1	0	0
3	0	1	0
4	0	0	0

 \ldots a function that separate inputs (data points) into classes

Suppose we have four data points

	x_1	x_2	у
1	1	1	1
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We may look for a **linear** function:

neuron : $(x_1 : \mathbb{R}) \to (x_2 : \mathbb{R}) \to (y : \mathbb{R})$ neuron $x_1 x_2 = b + w_{x_1} \times x_1 + w_{x_2} \times x_2$



Plotting these four data points in 3-dimensional space:





... a separating linear function:





Taking

neuron :
$$(x_1 : \mathbb{R}) \to (x_2 : \mathbb{R}) \to (y : \mathbb{R})$$

neuron $x_1 x_2 = b + w_{x_1} \times x_1 + w_{x_2} \times x_2$

here is its neuron view:





Taking

neuron :
$$(x_1 : \mathbb{R}) \to (x_2 : \mathbb{R}) \to (y : \mathbb{R})$$

neuron $x_1 x_2 = \mathbf{b} + \mathbf{w}_{x_1} \times x_1 + \mathbf{w}_{x_2} \times x_2$

here is its neuron view:





After running the training algorithm:

neuron :
$$(x_1 : \mathbb{R}) \to (x_2 : \mathbb{R}) \to (y : \mathbb{R})$$

neuron $x_1 x_2 = -0.9 + 0.5 \times x_1 + 0.5 \times x_2$



(This is one of infinitely many solutions)



Or may be we want to constrain the outputs:

neuron :
$$(x_1 : \mathbb{R}) \to (x_2 : \mathbb{R}) \to (y : \mathbb{R} \{ y = 0 \lor y = 1 \})$$

neuron $x_1 x_2 = S (-0.9 + 0.5x_1 + 0.5x_2)$



Or may be we want to constrain the outputs:

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neuron $x_1 x_2 = S(-0.9 + 0.5x_1 + 0.5x_2)$

where

$$S \ x = \begin{cases} 1, & \text{if } x \ge 0\\ 0, & \text{otherwise} \end{cases}$$



... are ideal for "perception" tasks:

- ▶ approximate functions when exact solution is hard to get
- ▶ tolerant to noisy and incomplete data



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BUT

- ▶ solutions not easily conceptualised (lack of explainability)
- ▶ prone to a new range of safety and security problems:

Neural networks



... are ideal for "perception" tasks:

- ▶ approximate functions when exact solution is hard to get
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BUT

 solutions not easily conceptualised (lack of explainability)
prone to a new range of safety and security problems: adversarial attacks data poisoning catastrophic forgetting

























the perturbations are imperceptible to human eye





the perturbations are imperceptible to human eye attacks transfer from one neural network to another





the perturbations are imperceptible to human eye attacks transfer from one neural network to another affect any domain where neural networks are applied



1943 Perceptron by McCullogh and Pitts



1943 Perceptron by McCullogh and Pitts90s - Rise of machine learning applications



1943 Perceptron by McCullogh and Pitts

- 90s Rise of machine learning applications
- 2013 C. Szegedy, W. Zaremba, I. Sutskever, J. Bruna, D. Erhan, I. Goodfellow, and R. Fergus. Intriguing properties of neural networks. 2013. (5000+ citations)

"The existence of the adversarial negatives appears to be in contradiction with the network's ability to achieve high generalization performance. Indeed, if the network can generalize well, how can it be confused by these adversarial negatives, which are indistinguishable from the regular examples? "

1943 Perceptron by McCullogh and Pitts90-2000 Rise of machine learning applications

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- 2013-.. Thousands of papers on adversarial training (in the attack-defence style)
 - A. C. Serban, E. Poll, J. Visser. Adversarial Examples A Complete Characterisation of the Phenomenon. 2019.



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 - $2017\,$ First Neural network verification attempts
 - G. Katz, C.W. Barrett, D.L. Dill, K. Julian, M.J. Kochenderfer: Reluplex: An Efficient SMT Solver for Verifying Deep Neural Networks. CAV (1) 2017: 97-117.
 - X. Huang, M. Kwiatkowska, S. Wang, M. Wu. Safety Verification of Deep Neural Networks. CAV (1) 2017: 3-29.

2017-.. Hundreds of papers on neural network verification









Verification of AI: Overview and Motivation

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Challenges of Neural Network Verification

Continuous Verification

Programs are functions...



 $Program: \mathcal{A} \to \mathcal{B}$

and so are neural networks:

 $NeuralNet: \mathbb{R}^n \to \mathbb{R}^m$

Neural Network Verification



... could be like any other verification task









I. The problem of opaque semantics



 $Program: \mathcal{A} \to \mathcal{B}$

 $NeuralNet: \mathbb{R}^n \to \mathbb{R}^m$

But normally, programs

have semantically meaningful parts which allows us to verify components that matter I. The problem of opaque semantics



 $Program: \mathcal{A} \to \mathcal{B}$

$NeuralNet: \mathbb{R}^n \to \mathbb{R}^m$

For neural nets:

I. The problem of opaque semantics



 $Program: \mathcal{A} \to \mathcal{B}$

$NeuralNet: \mathbb{R}^n \to \mathbb{R}^m$

For neural nets:

input and output are the only semantically meaningful parts (and even that is somewhat blurry)

The " ϵ -ball verification"





The " ϵ -ball verification"





An ϵ -ball $\mathbb{B}(\hat{x}, \epsilon) = \{x \in \mathbb{R}^n : ||\hat{x} - x|| \le \epsilon\}$

Classify all points in $\mathbb{B}(\hat{x}, \epsilon)$ in the "same class" as \hat{x} .



Take

neuron :
$$(x_1 : \mathbb{R}) \to (x_2 : \mathbb{R}) \to (y : \mathbb{R} \{ y = 0 \lor y = 1 \})$$

neuron $x_1 x_2 = S (-0.9 + 0.5x_1 + 0.5x_2)$



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Define

truthy
$$x = |1 - x| \le \epsilon$$

falsey $x = |0 - x| \le \epsilon$

Take



neuron :
$$(x_1 : \mathbb{R}) \to (x_2 : \mathbb{R}) \to (y : \mathbb{R} \{ y = 0 \lor y = 1 \})$$

neuron $x_1 x_2 = S (-0.9 + 0.5x_1 + 0.5x_2)$

Verify

test : $(x_1 : \mathbb{R} \{ \text{truthy } x_1 \}) \to (x_2 : \mathbb{R} \{ \text{truthy } x_2 \}) \to (y : \mathbb{R} \{ y = 1 \})$ test = neuron

Take



neuron :
$$(x_1 : \mathbb{R}) \to (x_2 : \mathbb{R}) \to (y : \mathbb{R} \{ y = 0 \lor y = 1 \})$$

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Verify

test : $(x_1 : \mathbb{R} \{ \text{truthy } x_1 \}) \to (x_2 : \mathbb{R} \{ \text{truthy } x_2 \}) \to (y : \mathbb{R} \{ y = 1 \})$ test = neuron



Wen Kokke, E.K., Daniel Kienitz, Robert Atkey and David Aspinall. 2020. Neural Networks, Secure by Construction: An Exploration of Refinement Types. APLAS'20.



data

Refinement type library for Neural Net Verification







Refinement type library for Neural Net Verification









NN as function; verification conditions as types

Refinement type library for Neural Net Verification











NN as function; verification conditions as types



Except you only see:







NN as function; verification conditions as types


- 1 Let Python process the data and find a suitable network
- 2 Export Python neural net to F* automatically:

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NB

Uniform syntax for all networks we obtain from Python code!

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- $1\,$ Let Python process the data and find a suitable network
- 2 Export Python neural net to F* automatically:
- 3 Define your verification conditions:

let eps = 0.1R let truthy x = 1.0R - eps \leq x && x \leq 1.0R + eps let falsey x = 0.0R - eps \leq x && x \leq 0.0R + eps val verify : (x₁ : \mathbb{R} {truthy x1}) \rightarrow (x₂ : \mathbb{R} { truthy x2}) \rightarrow (y : vector \mathbb{R} 1 {y == [1.0R]}) let verify x₁ x₂ = run model [x₁; x₂]

- 1 Let Python process the data and find a suitable network
- 2 Export Python neural net to F* automatically:
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Note: it is a universal property.

- 1 Let Python process the data and find a suitable network
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4 Type check and relax!



Wen Kokke, E.K., Daniel Kienitz, Robert Atkey and David Aspinall. 2020. Neural Networks, Secure by Construction: An Exploration of Refinement Types. APLAS'20.

▶ Builds on the real number library in F*;

- Concise Linear Algebra module;
- Straightforward definitions of neural nets as composed functions;
- ▶ with linear or "non-linear" activation functions
- ► A Python wrapper.



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Recall the 4 problems:

- I Semantics of function components is opaque
- II Number of verification parameters is huge
- III Undecidable verification for non-linear functions
- IV Finding verifiable neural networks is difficult



Recall the 4 problems:

- I Semantics of function components is opaque
- Use refinement types (for [functional] elegance),
- ... or SMT solvers directly.
 - Wen Kokke. 2020. Sapphire: a Neural Net Verification Library for Z3 in Python. https://github.com/wenkokke/sapphire
 - II Number of verification parameters is huge
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We get



Semantic Opacity

We get



Semantic Opacity $\longrightarrow \epsilon$ -ball verification

We get







Recall

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The " ϵ -ball verification"







MNIST data set

2828 images of the handwritten digits "0" to "9" $$784\ \rm{pixels}$ each



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The smallest network

input layer of 784 weights



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The smallest network

input layer of 784 weights hidden layer of (say) 128 ReLU nodes



MNIST data set

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The smallest network

input layer of 784 weights hidden layer of (say) 128 ReLU nodes output layer of 10 softmax neurons







We want to say:

```
val sample_in : vector R 784
let sample_in = let v = [7.394R; -0.451R; ...; 0.199R]
val sample_out: vector R 10
let sample_out = let v = [0.998R; 0.000R; ...; 0.000R]
```





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```

And prove the ϵ -ball property:

let _ = \forall (x:vector \mathbb{R} 784). (|sample_in - x| < 0.01R) \implies (|sample_out - (run network x)| < 0.1R))





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The smallest reasonable neural network

input layer of 784 weights hidden layer of (say) 128 ReLU nodes output layer of 10 softmax neurons





The smallest reasonable neural network

input layer of 784 weights

hidden layer of (say) 128 ReLU nodes

output layer of 10 softmax neurons

total $784 \times 128 + 128 + 128 \times 10 + 10 = 101770$ parameters



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Recall

- I Semantics of function components is mostly opaque
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Reduce the number of parameters (to scale)

either reduce network size and re-train or reduce the network to a provably equivalent or use over-approximation (in the style of abstract interpretation)

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- S.Gokulanathan, A.Feldsher, A.Malca, C.W. Barrett, G. Katz: Simplifying Neural Networks Using Formal Verification. NFM 2020: 85-93
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G.Singh, T.Gehr, M.Püschel, M.Vechev: An abstract domain for certifying neural networks. Proc. ACM Program. Lang. 3(POPL): 41:1-41:30 (2019)

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Semantic Opacity











Semantic Opacity







So far...











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Activation functions

$\mathbf{\nabla}$
•

Activation function	Equation	Example	1D Graph
Unit step (Heaviside)	$\phi(z) = \begin{cases} 0, & z < 0, \\ 0.5, & z = 0, \\ 1, & z > 0, \end{cases}$	Perceptron variant	
Sign (Signum)	$\phi(z) = \begin{cases} -1, & z < 0, \\ 0, & z = 0, \\ 1, & z > 0, \end{cases}$	Perceptron variant	
Linear	$\phi(z) = z$	Adaline, linear regression	
Piece-wise linear	$\phi(z) = \begin{cases} 1, & z \ge \frac{1}{2}, \\ z + \frac{1}{2}, & -\frac{1}{2} < z < \frac{1}{2}, \\ 0, & z \le -\frac{1}{2}, \end{cases}$	Support vector machine	
Logistic (sigmoid)	$\phi(z) = \frac{1}{1 + e^{-z}}$	Logistic regression, Multi-layer NN	
Hyperbolic tangent	$\phi(z) = \frac{e^z - e^{-z}}{e^z + e^{-z}}$	Multi-layer Neural Networks	
Rectifier, ReLU (Rectified Linear Unit)	$\phi(z)=max(0,z)$	Multi-layer Neural Networks	
Rectifier, softplus	$\phi(z) = \ln(1 + e^z)$	Multi-layer Neural Networks	

The SMT solver Z3:

- uses Dual Simplex to solve linear real arithmetic;
- and a fragment of non-linear real arithmetic – multiplications
- uses conflict resolution procedure
- based on cylindrical algebraic decomposition



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Jovanović, D., de Moura, L.: Solving non-linear arithmetic. ACM Communications in Computer Algebra 46(3/4), 104 (Jan 2013).



The SMT solver Z3:

- uses Dual Simplex to solve linear real arithmetic;
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We need:

- exponents
- logarithms
- trigonometric functions

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The solver MetiTarski:

Supports:



- ► logarithms
- trigonometric functions

for 4-5 variables



Akbarpour, B., Paulson, L.C.: MetiTarski: An automatic theorem prover for real-valued special functions. Journal of Automated Reasoning 44(3), 175–205 (Aug 2009).



The solver MetiTarski:

Supports:

- exponents
- ► logarithms
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for 4-5 variables

We need:

hundreds of variables

Akbarpour, B., Paulson, L.C.: MetiTarski: An automatic theorem prover for real- valued special functions. Journal of Automated Reasoning 44(3), 175–205 (Aug 2009).

Solutions?!



Linearise effectively!



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Solutions?!



Linearise effectively!



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(Re-)Train your network correct

Constraint-driven training



Train your network correct!

▶ augment loss functions with logical constraints

M.Fischer, M.Balunovic, D.Drachsler-Cohen, T.Gehr, C.Zhang, and M.Vechev. 2019. DL2: Training and Querying Neural Networks with Logic. ICML 2019, Vol. 97. PMLR, 1931–1941.

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- augment loss functions with abstract interpretation constraints
 - E.Ayers, F.Eiras, M.Hawasly, I.Whiteside: PaRoT: A Practical Framework for Robust Deep Neural Network Training. NFM 2020: 63-84
- M.Balunovic and M.Vechev. 2020. Adversarial Training and Provable Defenses: Bridging the Gap. ICLR 2020.

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A word of caution

Marco Casadio. Generative versus logical training against adversarial attacks. MSc Thesis at HWU. 2020.















Table of Contents



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Why Verifying Neural Networks?

Challenges of Neural Network Verification

Continuous Verification

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Continuous Verification



We have seen "continuous verification"

as a trend that arises everywhere in neural network verification

for a variety of different reasons!




Role of declarative programming:

 $\epsilon\text{-ball}$ verification is an instance of refinement type checking

 $\begin{array}{l} \text{verify } x: \ x: \mathbb{R}^n\{|\texttt{sample_in} - x| < \epsilon\} \Longrightarrow y: \mathbb{R}^m\{|\texttt{sample_out} - y| < \epsilon'\} \\ \text{verify } x = \texttt{run network } x \end{array}$

Wen Kokke, E.K., Daniel Kienitz, Robert Atkey and David Aspinall. 2020. Neural Networks, Secure by Construction: An Exploration of Refinement Types. APLAS'20.



Solvers are increasingly important for automation



Role of declarative programming:

Solvers are increasingly important for automation

Rise of domain-specific solvers for neural networks:

Katz, G., et al.: The Marabou framework for verification and analysis of deep neural networks. In: CAV 2019, Part I. LNCS, vol. 11561, pp. 443–452. Springer (2019)



- ▶ provide a sound and elegant PL infrastructure
- ▶ that bootstraps solvers and machine learning algorithms
- to ensure transparency, modularity,
- invariant and safety checks



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Role of declarative programming in <u>continuous</u> verification?

- Verification as refinement type checking
- ▶ Training as program synthesis

 $\begin{array}{ll} \text{verify } x: \ x: \mathbb{R}^n\{|\texttt{sample_in} - x| < \epsilon\} \Longrightarrow y: \mathbb{R}^m\{|\texttt{sample_out} - y| < \epsilon'\} \\ \text{verify } x = \texttt{run} & ?NETWORK? \quad x \end{array}$



Thanks for your attention!

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Open PhD position at LAIV

on verification of recurrent neural networks