

asymmetric barrier

CURRENT

(7.10.15)

$$D = \int (ipk - q^2) \psi^* - iq (p+iq) \psi = -(ipk - q^2) \psi^* - q (ip - q) \psi$$

$$I = (q^2 \psi^* + q^2 \psi)$$

$$|T^{\rightarrow}|^2 = \left(\frac{p}{k}\right)^2 |T^{\rightarrow}|^2 \quad \boxed{|T^{\leftarrow}|^2 = \frac{p^2}{k^2} |T^{\rightarrow}|^2}$$

~~$$|R^{\rightarrow}|^2 = q^2$$~~

$$\vec{j}_L^{\rightarrow} = \frac{e\hbar k}{m} (1 - |R^{\rightarrow}|^2), \quad \vec{j}_R^{\rightarrow} = \frac{e\hbar p}{m} |T^{\rightarrow}|^2$$

$$\vec{j}_L^{\leftarrow} = -\frac{e\hbar k}{m} |T^{\leftarrow}|^2 = -\frac{e\hbar k}{m} \frac{p^2}{k^2} |T^{\rightarrow}|^2 = -\frac{e\hbar p^2}{mk} |T^{\rightarrow}|^2$$

$$\boxed{\vec{j}_L^{\text{tot}} = \frac{e\hbar k}{m} [1 - |R^{\rightarrow}|^2 - |T^{\leftarrow}|^2]}$$

$$\vec{j}_R^{\leftarrow} = -\frac{e\hbar p}{m} (1 - |R^{\leftarrow}|^2)$$

$$\boxed{\vec{j}_R^{\text{tot}} = \frac{e\hbar p}{m} [ |T^{\rightarrow}|^2 - 1 + |R^{\leftarrow}|^2]}$$

~~$$\vec{j}_L^{\text{tot}} = \frac{e\hbar k}{m} \left[ 1 - \frac{q^2(qs-kc)^2 + p^2(qc+ks)^2}{q^2(qs+kc)^2 + p^2(qc+ks)^2} - \frac{4q^2p^2}{\dots} \right]$$

$$= \frac{e\hbar k}{m} \frac{q^2(qs+kc)^2 + p^2(qc+ks)^2 - q^2(qs-kc)^2 - p^2(qc+ks)^2 - 4q^2p^2}{\dots} = \frac{e\hbar k}{m} \frac{A}{B}$$~~

~~$$A = q^2(qs+ks + qs-kc)(qs+kc - qs+kc) - 4q^2p^2$$

$$= q^2(2qs)(2kc) - 4q^2p^2 = 4q^3kcs - 4q^2p^2 = 4q^2(qkcs - p^2)$$~~

~~$$\boxed{\vec{j}_L^{\text{tot}} = \frac{e\hbar k}{m} \frac{4q^2(qkcs - p^2)}{q^2(qs+kc)^2 + p^2(qc+ks)^2}}$$~~

~~$$\vec{j}_R^{\text{tot}} = \frac{e\hbar p}{m} \left[ -1 + \frac{4k^2q^2}{\dots} + 1 \right] = \frac{e\hbar p}{m} \frac{4k^2q^2}{\dots}$$~~

$$|U \leq E < U + V_0| \quad \underline{q \rightarrow iq \text{ only}} \quad \boxed{S \rightarrow iS, c \rightarrow c}$$

$$T \rightarrow = \frac{2iqk e^{-ipd}}{iq(p+k)c - i(-q^2 + pk)is}$$

$$= \frac{2iqk e^{-ipd}}{iq(p+k)c + (-q^2 + pk)s}$$

$$\boxed{|T \rightarrow|^2 = \frac{4q^2 k^2}{(q^2 - pk)^2 s^2 + q^2 (p+k)^2 c^2}}$$

$$R \rightarrow = \frac{iq(k-p)c + i(-q^2 - pk)is}{iq(k+p)c - i(-q^2 + pk)is} = \frac{iq(k-p)c + (q^2 + pk)s}{iq(k+p)c + (-q^2 + pk)s}$$

$$\boxed{|R \rightarrow|^2 = \frac{q^2(k-p)^2 c^2 + (q^2 + pk)^2 s^2}{q^2(k+p)^2 c^2 + (q^2 - pk)^2 s^2}}$$

$$T \leftarrow = \frac{2iqp e^{-ipd}}{iq(k+p)c - i(-q^2 + pk)is} = \frac{2iqp e^{-ipd}}{iq(k+p)c + (-q^2 + pk)s}$$

$$\boxed{|T \leftarrow|^2 = \frac{4q^2 p^2}{q^2(k+p)^2 c^2 + (q^2 - pk)^2 s^2} \equiv \frac{p^2}{k^2} |T \rightarrow|^2}$$

$$R \leftarrow = e^{-2ipd} \frac{iq(p-k)c + i(-q^2 - kp)is}{iq(p+k)c - i(-q^2 + kp)is} = e^{-2ipd} \frac{iq(p-k)c + (q^2 + pk)s}{iq(p+k)c + (-q^2 + kp)s}$$

$$\boxed{|R \leftarrow|^2 = \frac{q^2(p-k)^2 c^2 + (q^2 + pk)^2 s^2}{q^2(p+k)^2 c^2 + (q^2 - pk)^2 s^2} \equiv |R \rightarrow|^2}$$

$$1 - |R^{\rightarrow}|^2 - |T^{\leftarrow}|^2 = 1 - \frac{q^2(k-p)^2 c^2 + (q^2 + pk)^2 s^2}{q^2(k+p)^2 c^2 + (q^2 - pk)^2 s^2} - \frac{4q^2 p^2}{\dots}$$

$$= \frac{1}{\dots} \left\{ \underbrace{q^2(k+p)^2 c^2 + (q^2 - pk)^2 s^2}_{\dots} - \underbrace{q^2(k-p)^2 c^2 + (q^2 + pk)^2 s^2}_{\dots} - 4q^2 p^2 \right\}$$

$$\{ \dots \} = q^2 c^2 [(k+p)^2 - (k-p)^2] + s^2 [(q^2 - pk)^2 - (q^2 + pk)^2] - 4q^2 p^2$$

$$= q^2 c^2 \cdot 4kp + s^2 \cdot 4q^2 pk - 4q^2 p^2 = 4q^2 kp \underbrace{(c^2 - s^2)}_1 - 4q^2 p^2$$

$$= 4q^2 kp - 4q^2 p^2 = 4q^2 p(k-p)$$

$$\boxed{j_{L}^{\text{tot}} = \frac{e\hbar k}{m} \frac{4q^2 p(k-p)}{\dots}}$$

$$|T^{\rightarrow}|^2 - 1 + |R^{\leftarrow}|^2 = \frac{4q^2 k^2}{\dots} - 1 + \frac{q^2(p-k)^2 c^2 + (q^2 + pk)^2 s^2}{\dots}$$

$$= \frac{1}{\dots} \left\{ 4q^2 k^2 - \underbrace{q^2(k+p)^2 c^2 + (q^2 - pk)^2 s^2}_{\dots} + \underbrace{q^2(p-k)^2 c^2 + (q^2 + pk)^2 s^2}_{\dots} \right\}$$

$$= \frac{1}{\dots} \left\{ 4q^2 k^2 + \underbrace{q^2 c^2 [(k+p)^2 - (p-k)^2]}_{4kp} + \underbrace{s^2 [(q^2 - pk)^2 - (q^2 + pk)^2]}_{-4q^2 pk} \right\}$$

$$= \frac{1}{\dots} \left\{ 4q^2 k^2 - 4q^2 kpc^2 + 4q^2 kps^2 \right\} = \frac{4q^2 k}{\dots} \left\{ k - pc^2 + ps^2 \right\}$$

$$= \frac{4q^2 k}{\dots} (k-p) \rightarrow \boxed{j_{R}^{\text{tot}} = \frac{e\hbar p}{m} \frac{4q^2 k(k-p)}{\dots}} \equiv j_{L}^{\text{tot}}$$