

1.1.5 Substitutions

$$\int \dots \int f(x_1, \dots, x_N) dx_1 \dots dx_N = \int \dots \int \underbrace{\tilde{f}(y_1, \dots, y_N)}_{f(x_1(y), \dots, x_N(y))} dy_1 \dots dy_N$$

$$y = \frac{\partial(x_1, \dots, x_N)}{\partial(y_1, \dots, y_N)} \quad \text{where} \quad \begin{aligned} x_1 &= x_1(y_1, \dots, y_N) = x_1(y), \\ x_2 &= x_2(y), \dots, x_N = x_N(y) \end{aligned}$$

• Integral eq.

$$y(t) = x(t) + \lambda \int_a^b K(t, s) x(s) ds$$

If $K(t, s) = 0$ for $s > t \Rightarrow y(t) = x(t) + \lambda \int_a^t K(t, s) x(s) ds$

• If $K(t, s)$ does not depend on t , then $y(t) = x(t) + \lambda \int_a^t K(s) x(s) ds$

$K(t, s)$ must be discontinuous at $s = t$:

$$\dot{y} = \dot{x} + \lambda K(t, t) x(t) + \lambda \int_a^t (\partial_t K(t, s)) x(s) ds$$

If $K(t, s)$ does not depend on t , then $\partial_t K = 0$ and $\dot{y} = \dot{x} + \lambda K(t, t) x(t)$

If $K(t, t) = 0$, then $y(t) = x(t) + C$, i.e. this substitution is not good.

Normally, via averaging:

$$K(t) = \frac{1}{2} \left[\underbrace{K(t+0, s)}_0 + K(t-0, s) \right]_{t \rightarrow s} = \frac{1}{2} K(s-0, s)$$

$$= \frac{1}{2} K(t, s) \big|_{t \rightarrow s=0}$$

(1.1.124)

Let us start the Jacobian in this case:

$$y(t) = x(t) + \lambda \int_a^t K(s) x(s) ds, \quad K(t) = \frac{1}{2}$$

$$\hookrightarrow y_i = x_i + \lambda \left(K_1 x_1 + \dots + \frac{1}{2} K_N x_N \right) \varepsilon$$

which is:

$$y_1 = x_1 + \lambda \frac{1}{2} K_1 x_1 \varepsilon$$

$$y_2 = x_2 + \lambda \left(K_1 x_1 + \frac{1}{2} K_2 x_2 \right) \varepsilon$$

$$y_3 = x_3 + \lambda \left(K_1 x_1 + K_2 x_2 + \frac{1}{2} K_3 x_3 \right) \varepsilon, \dots$$

$$\left(\frac{\partial Y}{\partial X} \right) = \begin{vmatrix} 1 + \frac{1}{2} \lambda k_1 \varepsilon & 0 & 0 & 0 & 0 \\ \lambda k_1 & 1 + \frac{1}{2} \lambda k_2 \varepsilon & 0 & 0 & 0 \\ \lambda k_1 & \lambda k_2 & 1 + \frac{1}{2} \lambda k_3 \varepsilon & 0 & 0 \\ \lambda k_1 & \lambda k_2 & \lambda k_3 & 1 + \frac{1}{2} \lambda k_4 \varepsilon & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \end{vmatrix}$$

$$= \prod_{i=1}^N \left(1 + \frac{1}{2} \lambda k_i \varepsilon \right) = \prod_{i=1}^N \exp \left[\frac{1}{2} \lambda k_i \varepsilon + O(\varepsilon^2) \right] \rightarrow \exp \left[\int_a^t \frac{1}{2} \lambda K(s) ds \right]$$

$$\boxed{Y(\lambda) = \exp \left[\frac{\lambda}{2} \int_a^t K(s) ds \right]} \quad (1.1.127)$$

Example

$$\int_{C[0,0;t]} d_w y(\tau) = 1 \quad (1.1.128)$$

Change of function: $y(t) = x(t) - \int_0^t ds \frac{\ddot{Q}(s)}{\dot{Q}(s)} x(s)$ (1.1.129)

where $\ddot{Q}(s) + p(s)Q(s) = 0$, $Q(t) = 1$, $\dot{Q}(t) = 0$ (1.1.130)

We have after the substitution: ($\mathcal{D} = 1$ here again)

$$\int_{C[0,0;t]} d_w y(\tau) = \int_{C[0,0;t]} \frac{dx(\tau)}{\sqrt{\pi} d\tau} \int_{C[0,0;t]} \prod_{\tau=0}^t \frac{dy(\tau)}{\sqrt{\pi} d\tau} \exp \left[- \int_0^t \dot{y}^2(\tau) d\tau \right]$$

$$= \int \prod_{\tau=0}^t \frac{dx(\tau)}{\sqrt{\pi} d\tau} \exp \left[- \int_0^t d\tau \left(\dot{x} - \frac{\dot{Q}}{Q} x \right)^2 \right] \underbrace{\exp \left[- \frac{1}{2} \int_0^t \frac{\ddot{Q}(s)}{\dot{Q}(s)} ds \right]}_{\text{Jacobian}}$$

Here

$$\int_0^t \frac{\dot{Q}(s)}{Q(s)} ds = \int \frac{dQ(s)}{Q(s)} = \ln |Q(s)| \Big|_0^t = \underbrace{\ln Q(t)}_{=0} - \ln Q(0) =$$

$$= -\ln Q(0), \text{ since } Q(t) = 1, \text{ and hence}$$

$$\exp \left[- \frac{1}{2} \int_0^t \frac{\dot{Q}(s)}{Q(s)} ds \right] = \exp \left[+ \frac{1}{2} \ln Q(0) \right] = \sqrt{Q(0)}$$

The other exponent contains the integral,

$$\int_0^t d\tau (\dot{x} - \frac{\dot{Q}}{Q} x)^2 = \int_0^t \dot{x}^2 d\tau + \int_0^t d\tau \left(\frac{\dot{Q}}{Q}\right)^2 x^2 - 2 \int_0^t d\tau \dot{x} \frac{\dot{Q}}{Q} x$$

Here $2 \int_0^t d\tau \underbrace{x \cdot \dot{x}}_{dx^2} \frac{\dot{Q}}{Q} \xrightarrow{\text{by parts}} x^2 \frac{\dot{Q}}{Q} \Big|_0^t - \int_0^t x^2 \left(\frac{\dot{Q}}{Q}\right)' d\tau$

$$= x^2(t) \frac{\dot{Q}(t)}{Q(t)} - \underbrace{x^2(0)}_{(C[0,0;t]!)} \frac{\dot{Q}(0)}{Q(0)} - \int_0^t d\tau \frac{d}{d\tau} \left(\frac{\dot{Q}}{Q}\right) x^2(t) \quad \text{by parts}$$

$$= \cancel{\frac{\dot{Q}}{Q} x^2(t)} = - \int_0^t d\tau \frac{\ddot{Q} Q - (\dot{Q})^2}{Q^2} x^2 = - \int_0^t \frac{\ddot{Q}}{Q} x^2 d\tau + \int_0^t d\tau \left(\frac{\dot{Q}}{Q}\right)^2 x^2$$

so that

$$\begin{aligned} \int_0^t d\tau (\dot{x} - \frac{\dot{Q}}{Q} x)^2 &= \int_0^t \dot{x}^2 d\tau + \int_0^t d\tau \left(\frac{\dot{Q}}{Q}\right)^2 x^2 + \int_0^t \frac{\ddot{Q}}{Q} x^2 d\tau - \int_0^t d\tau \left(\frac{\dot{Q}}{Q}\right)^2 x^2 \\ &= \int_0^t \dot{x}^2 d\tau + \int_0^t \frac{\ddot{Q}}{Q} x^2 d\tau \end{aligned}$$

But $\ddot{Q} = -p(\tau) Q(\tau) \Rightarrow \int_0^t \dot{x}^2 d\tau + \int_0^t (-p(\tau)) x^2(\tau) d\tau$

Therefore,

$$\int_{C[0,0;t]} d_W y(\tau) = \int \prod_{\tau=0}^t \frac{dx(\tau)}{\sqrt{Q(\tau)}} \exp\left[-\int_0^t \dot{x}^2 d\tau\right] \exp\left[+\int_0^t p(\tau) x^2(\tau) d\tau\right] x$$

$$x \sqrt{Q(0)} \equiv \sqrt{Q(0)} I_4,$$

where I_4 we considered above (with $p'(\tau) \equiv -p(\tau)$)

The result was $I_4 = 1/\sqrt{Q(0)}$. We get the same as our

$$\int_{C[0,0;t]} = 1 \rightarrow I_4 = 1/\sqrt{Q(0)}$$

• Example: correlation function. -43-

$$F[x(t)] = x(s)x(p), \quad s, p - \text{two fixed times}$$

$$t_0 < s < p < t$$

$$\int_{C[0, t_0; t]} d_w x(\tau) \cdot x(s)x(p) \stackrel{\text{def}}{=} \langle x(s)x(p) \rangle_w$$

We have: (still 4D=1):

$$\begin{aligned} \int_{C[0, t_0; t]} &= \int_{-\infty}^{\infty} dx_s dx_p \cdot x_s x_p \cdot \underbrace{\int_{C[0, t_0; x_s, s]} d_w x(\tau)}_{=1} \times \underbrace{\int_{C[x_s, s; x_p, p]} d_w x(\tau)}_{=1} \times \\ &\times \underbrace{\int_{C[x_p, p; t]} d_w x(\tau)}_{=1} \frac{1}{\sqrt{\pi(s-t_0)}} \exp\left[-\frac{x_s^2}{s-t_0}\right] \frac{1}{\sqrt{\pi(p-s)}} \exp\left[-\frac{(x_p-x_s)^2}{p-s}\right] \\ &= 1 \end{aligned}$$

$$= \int_{-\infty}^{\infty} dx_s dx_p \frac{1}{\sqrt{\pi(s-t_0)}\sqrt{\pi(p-s)}} e^{-\frac{x_s^2}{s-t_0}} e^{-\frac{(x_p-x_s)^2}{p-s}} \cdot x_s x_p$$

Here

$$\int_{-\infty}^{\infty} dx_p x_p e^{-\frac{(x_p-x_s)^2}{p-s}} = \int_{-\infty}^{\infty} dx_p (x_p - x_s) e^{-\frac{(x_p-x_s)^2}{p-s}} + x_s \int_{-\infty}^{\infty} e^{-\frac{(x_p-x_s)^2}{p-s}} dx_p =$$

$$= \underbrace{\int_{-\infty}^{\infty} (x_p - x_s) e^{-\frac{(x_p-x_s)^2}{p-s}} dx_p}_0 + x_s \underbrace{\int_{-\infty}^{\infty} e^{-\frac{(x_p-x_s)^2}{p-s}} dx_p}_{\sqrt{\pi(p-s)}}$$

$$= \sqrt{\pi(p-s)} \cdot x_s$$

Then,

$$\int_{-\infty}^{\infty} dx_s x_s^2 \frac{1}{\sqrt{\pi(s-t_0)}} e^{-\frac{x_s^2}{s-t_0}} = \frac{1}{\sqrt{\pi(s-t_0)}} \cdot \frac{\sqrt{\pi}}{2 \left(\frac{1}{s-t_0}\right)^{3/2}}$$

$$= \frac{1}{2} (s-t_0), \quad (s < p);$$

$$\boxed{\int_{C[0, t_0; t]} d_w x(\tau) x(s)x(p) = \frac{1}{2} \min(s-t_0, p-t_0)} \quad (1.1.13)$$

Example

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s-fixed time ($< t$):

$$\frac{1}{\sqrt{\pi s}} e^{-x_s^2/s}$$

$$I_2^{\text{cond}} = \int_{C[0,0;X,t]} d_w X(\tau) X(s) = \int_{-\infty}^{\infty} dX_s \cdot X_s \int_{C[0,0;X_s,s]} d_w X(\tau) X$$

$$\underbrace{X \int_{C[X_s,s;X,t]} d_w X(\tau)}_{\frac{1}{\sqrt{\pi(t-s)}} \exp\left(-\frac{(X-X_s)^2}{t-s}\right)} = \int_{-\infty}^{\infty} dX_s \cdot X_s \frac{1}{\sqrt{\pi s}} \frac{1}{\sqrt{\pi(t-s)}} e^{-X_s^2/s} e^{-\frac{(X-X_s)^2}{t-s}}$$

Here $-\frac{X_s^2}{s} - \frac{(X-X_s)^2}{t-s} = -\frac{X^2}{t} - \frac{t}{s(t-s)} \left(X_s - \frac{s}{t}X\right)^2$

$$\hookrightarrow \int_{-\infty}^{\infty} X_s \exp\left[-\frac{t}{s(t-s)} \left(X_s - \frac{s}{t}X\right)^2\right] dX_s = \int \left(X_s - \frac{s}{t}X\right) \exp[\dots] dX_s$$

$$+ \frac{s}{t}X \int \underbrace{\exp[\dots]}_{\frac{1}{\sqrt{\pi(t-s)s}}} dX_s = \frac{s}{t}X \cdot \cancel{\sqrt{\frac{t}{\pi(t-s)s}}} \sqrt{\frac{\pi(t-s)s}{t}}$$

so that

$$I_2^{\text{cond}} = \frac{1}{\sqrt{\pi s} \sqrt{\pi(t-s)}} \frac{s}{t} X \cdot \frac{\sqrt{\pi(t-s)s}}{\sqrt{t}} e^{-X^2/t}$$

$$= \frac{Xs}{\sqrt{\pi} t^{3/2}} e^{-X^2/t}$$