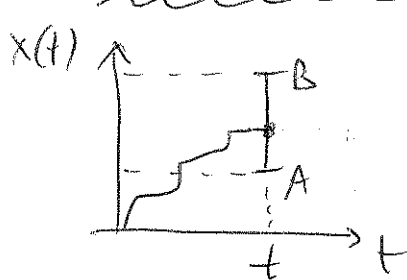


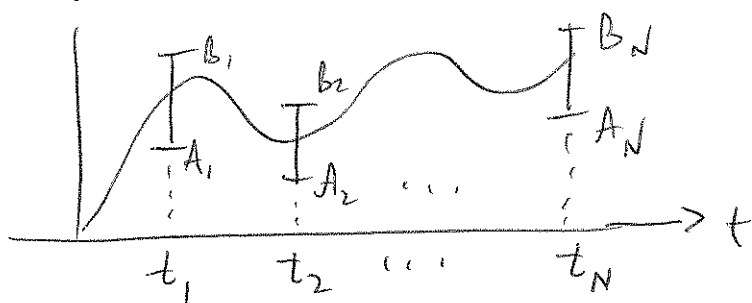
1.1.2. Wiener's path integrals



$$\mathbb{P}[x(t) \in [A, B]] = \int_A^B dx \, W(x, t) \quad (1.1.48)$$

↳ to be anywhere within $x \in [A, B]$ at t .

Probability to go inside a tube of 'gates':



a product of individual probabilities

↑
Markov chain

$$\mathbb{P}[x(t_1) \in [A_1, B_1]; \dots; x(t_N) \in [A_N, B_N]] =$$

$$= \int_{A_1}^{B_1} dx_1 W(x_1 - x_0, t_1 - t_0) \times \int_{A_2}^{B_2} dx_2 W(x_2 - x_1, t_2 - t_1) \times \dots \times$$

$$\times \int_{A_N}^{B_N} dx_N W(x_N - x_{N-1}, t_N - t_{N-1}) = \left(\begin{array}{l} \text{assuming } t_0 = 0 \\ \text{and } x_0 = 0 \end{array} \right) =$$

$$= \int_{A_1}^{B_1} dx_1 \frac{e^{-x_1^2/4Dt_1}}{\sqrt{4\pi Dt_1}} \times \int_{A_2}^{B_2} dx_2 \frac{e^{-(x_2 - x_1)^2/4D(t_2 - t_1)}}{\sqrt{4\pi D(t_2 - t_1)}} \times \dots$$

$$\dots \times \int_{A_N}^{B_N} dx_N \frac{e^{-(x_N - x_{N-1})^2/4D(t_N - t_{N-1})}}{\sqrt{4\pi D(t_N - t_{N-1})}} \quad (1.1.50)$$

- Stochastic process is obtained via a continuous limit of time increments

$$\Delta t = t_i - t_{i-1} \rightarrow 0, \quad 1 \leq i \leq N \quad (N \rightarrow \infty)$$

For a general Markov process

$$W(x, t | x_0, t_0) dx \stackrel{\Delta t}{=} \mathbb{P} \left[x(t) \in [x, x+dx], \text{ given } x(t_0) = x_0 \right]_{t > t_0}$$

Initially, $w(x, t) = \delta(x - x_0)$ at $t \rightarrow t_0$, and the transition probabilities become Gaussian $\rightarrow$ Wiener process.

- Probability for the brownian particle moves along $x(t)$ via an ∞ number of 'gates' (combining all exponents):

$$\lim_{\substack{\Delta t_i \rightarrow 0 \\ N \rightarrow \infty}} \exp \left\{ - \sum_{i=1}^N \frac{(x_i - x_{i-1})^2}{4D(t_i - t_{i-1})} \right\} \prod_{i=1}^N \frac{dx_i}{\sqrt{4\pi D(t_i - t_{i-1})}}$$

Here $\exp\{\dots\}$ can be also rewritten as:

$$\begin{aligned} \exp\{\dots\} &= \exp \left\{ - \sum_{i=1}^N \frac{(x_i - x_{i-1})^2}{4D(t_i - t_{i-1})^2} \Delta t_i \right\} = \\ &= \exp \left\{ - \sum_{i=1}^N \frac{1}{4D} \dot{x}_i^2 \Delta t_i \right\} = \exp \left\{ - \frac{1}{4D} \int_0^t \dot{x}^2 d\tau \right\} \end{aligned}$$

and we arrive at the probability for a single trajectory:

$$\lim_{\Delta t \rightarrow 0} \left[\exp \left\{ - \frac{1}{4D} \int_0^t d\tau \dot{x}(\tau)^2 \right\} \prod_{\tau=0}^t \frac{dx(\tau)}{\sqrt{4\pi D d\tau}} \right] \quad \begin{array}{l} \text{probability} \\ \text{inside} \\ \text{thin} \\ \text{tube around} \\ x(\tau) \end{array} \quad (1.1.51)$$

• Notations:

$C(x_1 t_1; x_2 t_2)$ - all trajectories starting at $x_1 t_1$, ending at $x_2 t_2$.

$C(x_1 t_1; [A, B], t_2)$ - ending at the gate $[A, B]$;

$C(x_1, t_1; t_2)$ - for $[A, B]$ (ending gate) to be from the whole $\mathbb{R}$.

For instance, $C(0, 0; t)$ - all trajectories starting at the origin and ending anywhere.

• Probability to find the particle at the gate $[A, B]$:

$$P[x(t) \in [A, B]] = \int C[0, 0; [A, B], t] \exp\left\{-\frac{1}{4D} \int_0^t d\tau \dot{x}(\tau)^2\right\} \prod_{\tau=0}^t \frac{dx(\tau)}{\sqrt{4\pi D d\tau}} \quad (1.1.52)$$

At the same time, this probability is

sum over a continuous set of all trajectories

$$\int_A^B dx \, w(x, t) = \int_A^B dx \, \frac{1}{\sqrt{4\pi Dt}} e^{-x^2/4Dt} \equiv$$

If $A=B=x_t$, then

$$P[x(t) \equiv x_t] = \int C[0, 0; x_t, t] \underbrace{d_w x(\tau)}_{\text{Wiener measure}} \quad (1.1.53)$$

$$\equiv \frac{1}{\sqrt{4\pi Dt}} \exp\left(-\frac{x_t^2}{4Dt}\right)$$

Here the measure is conditional since x_t is fixed. The measure

in $\int C[0, 0; t] d_w x(\tau)$ is unconditional.

Also,

$$\int C[0, 0; t] d_w x(\tau) = 1 \quad (1.1.55)$$

is not a multiple number at t

Obviously:

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$$\underbrace{\int_{C[0,0;t]} d_w x(\tau)}_{\text{all possible endpoints}} = \int_{-\infty}^{\infty} dx_t \underbrace{\int_{C[0,0;x_t,t]} d_w x(\tau)}_{\text{fixed endpoints at } x_t} \quad (1.1.56)$$

• ESKC condition.

$$W(x-x_0, t-t_0) = \int_{-\infty}^{\infty} dx' W(x-x', t-t') W(x'-x_0, t'-t_0)$$

in terms of Wiener's integrals:

$$\boxed{\int_{C[x_0,t_0;x,t]} d_w x(\tau) = \int_{-\infty}^{\infty} dx' \int_{C[x',t';x,t]} d_w x(\tau) \int_{C[x_0,t_0;x',t']} d_w x(\tau)} \quad (1.1.58)$$

which means that the integral over paths can always be split into a product of integrals over smaller paths.

1.1.3. Wiener's Theorem

- The Wiener path integral $= 0$ for any discontinuous or differentiable trajectory.

(A) Discontinuous trajectories

$0 < t < 1$ is split into 2^m intervals to

$$t_j = \frac{j}{2^m} \quad j=0, \dots, 2^m-1 \quad \left| \quad t_0=0 \quad t_1=\frac{1}{2^m} \quad t_2=\frac{2}{2^m} \quad \dots \quad t_m=1 \right.$$

Consider all $x(t)$ which have a discontinuity:

$$\cancel{x(t_j)} \quad \cancel{x(t_{j+1})} \quad |x(t_{j+1}) - x(t_j)| > \frac{h}{A^m} \quad (1.1.64)$$

$$h > 0, \quad A \in [1, \sqrt{2}].$$

We shall also use $D = 1/4 \rightarrow W(x, t | 0, 0) = \frac{1}{\sqrt{\pi t}} e^{-x^2/t}$ for the transition probability.

Step 1 Estimate the measure for all trajectories which are discontinuous as in (1.1.64)

$$\int d_W x(\tau) \underbrace{\chi[x(\tau)]}_{\begin{array}{l} \rightarrow 1, \text{ if } x(\tau) \text{ satisfies (1.1.64)} \\ \quad 0, \text{ if } x(\tau) \text{ does not} \end{array}} =$$

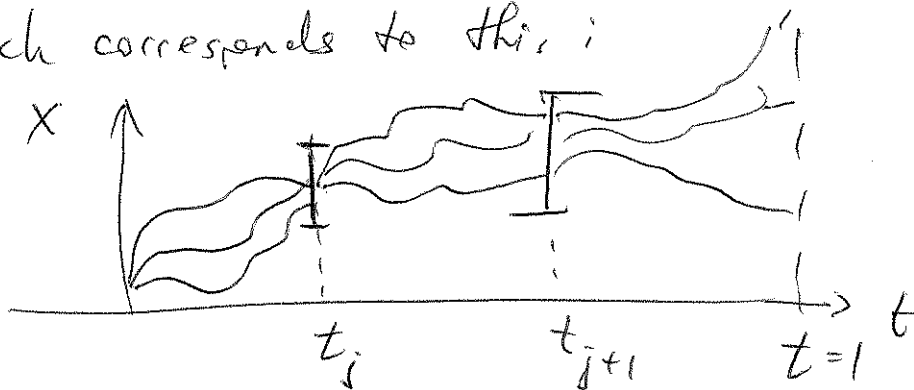
$$\Rightarrow \int dx_1 dx_2 \int_{|x_1 - x_2| > \frac{h}{A^m}} C[0,0; x_1, x_2]$$

$$\text{Let } x_{j+1} = x(t_{j+1}), \quad x_j = x(t_j), \text{ then}$$

$$\Rightarrow \int_{|x_{j+1} - x_j| > h/A^m} dx_{j+1} dx_j \cdot \int d_W x(\tau) \cdot$$

$$\times \int_{C[x_j, t_j; x_{j+1}, t_{j+1}]} d_w x(\tau) \times \int_{C[x_{j+1}, t_{j+1}; t=1]} d_w x(\tau)$$

which corresponds to this:



The last integral = 1 (normalisation, it should arrive somewhere). Also,

$$\int_{C[x, t | x', t']} d_w x(\tau) = \frac{1}{\sqrt{j_1(t'-t)}} e^{-\frac{(x'-x)^2}{(t'-t)}}$$

so that

$$\int_{C[0,0;t]} d_w x(\tau) \overbrace{\chi[x(\tau)]}^{\text{functional}} = \left| \begin{matrix} \xi_1 = x_{j+1} \\ \xi_2 = x_j \end{matrix} \right|$$

$$= \int_{|\xi_1 - \xi_2| > \frac{h}{A_m}} d\xi_1 d\xi_2 \cdot \frac{1}{\sqrt{\pi \frac{j}{2^m}}} e^{-\frac{\xi_1^2}{(j/2^m)}} \cdot \frac{1}{\sqrt{\pi \left(\frac{(j+1)}{2^m} - \frac{j}{2^m} \right)}} e^{-\frac{(\xi_1 - \xi_2)^2}{1/2^m}}$$

$$= \sqrt{\frac{2^m}{\pi j}} \sqrt{\frac{2^m}{\pi}} \int_{|\xi_1 - \xi_2| > \frac{h}{A_m}} d\xi_1 d\xi_2 e^{-2^m \xi_1^2 / j} e^{-2^m (\xi_1 - \xi_2)^2}$$

Making change of variables:

$$(\xi_1 - \xi_2) 2^{m/2} = \eta, \quad \xi_1 = \zeta \rightarrow \begin{cases} \xi_1 = \zeta \\ \xi_2 = \zeta - \eta 2^{-m/2} \end{cases}$$

Jacobian:

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$$\frac{\partial(\xi_1, \xi_2)}{\partial(\eta, \zeta)} = \begin{vmatrix} \partial \xi_1 / \partial \eta & \partial \xi_2 / \partial \eta \\ \partial \xi_1 / \partial \zeta & \partial \xi_2 / \partial \zeta \end{vmatrix} = \begin{vmatrix} 0 & -2^{-m/2} \\ 1 & 1 \end{vmatrix} = 2^{-m/2}$$

$$\hookrightarrow 2^{-m/2} \frac{2^m}{\pi \sqrt{j}} \int d\eta \int d\zeta e^{-\left(\frac{2^m}{j}\right) \cdot \zeta^2} e^{-2^m \eta^2 / 2^m} =$$

$$= \frac{2^{m/2}}{\sqrt{j} \pi} \int d\eta e^{-\eta^2} \left[\int_{-\infty}^{\infty} d\zeta e^{-\left(\frac{2^m}{j}\right) \zeta^2} \right]$$

$$|\eta| > h(\sqrt{2}/A)^m$$

$$\sqrt{\frac{\pi}{2^m/j}} = \sqrt{\frac{\pi j}{2^m}} = \sqrt{\pi j} 2^{-m/2}$$

$$= \frac{1}{\sqrt{\pi}} \int_{|\eta| > h(\sqrt{2}/A)^m} d\eta e^{-\eta^2} = \frac{2}{\sqrt{\pi}} \int_{h(\sqrt{2}/A)^m}^{\infty} e^{-\eta^2} d\eta$$

We use inequality (Abramowitz & Stegun):

$$\int_x^{\infty} e^{-t^2} dt \leq \frac{e^{-x^2}}{x + \sqrt{x^2 + \frac{1}{\pi}}} < \frac{e^{-x^2}}{2x} \text{ as } x + \sqrt{x^2 + \frac{1}{\pi}} > 2x$$

Then,

$$\int_{C[0,0;t]} d\omega X(\tau) X[X/\theta] = \frac{2}{\sqrt{\pi}} \int_{h\theta^m}^{\infty} e^{-\eta^2} d\eta <$$

$$< \frac{2}{\sqrt{\pi}} \frac{e^{-h^2 \theta^{2m}}}{2h\theta^m} = \frac{e^{-h^2 \theta^{2m}}}{\sqrt{\pi} h \theta^m}, \quad \theta = \sqrt{2}/A.$$

$$\therefore 1 < \theta < \sqrt{2} \text{ as } 1 < A < \sqrt{2}.$$

Step 2 Estimate the measure for all trajectories from (1.1.64) for all possible m and j :

$$\leq \sum_{m=1}^{\infty} \sum_{j=0}^{2^m-1} \frac{e^{-h^2 \theta^{2m}}}{\sqrt{h} \theta^m} = \sum_{m=1}^{\infty} 2^m \frac{e^{-h^2 \theta^{2m}}}{\sqrt{h} \theta^m} =$$

$$= \frac{1}{h\sqrt{\pi}} \sum_{m=1}^{\infty} e^{-h^2 \theta^{2m}} \cdot \left(\frac{2}{\theta}\right)^m$$

Since $1 < \theta < \sqrt{2}$, $\theta^2 \in [1, 2]$ ~~$e^{-h^2 \theta^{2m}} < e^{-h^2}$~~
 For large $h \rightarrow \infty$ $h^2 > m/(\theta^{2m}-1)$, then

$$e^{-h^2 \theta^{2m}} \leq e^{-h^2 (\theta^{2m}-1)} e^{-h^2} < e^{-h^2} e^{-m}$$

$$\hookrightarrow \frac{1}{h\sqrt{\pi}} \sum_{m=1}^{\infty} e^{-h^2} \left(\frac{2}{\theta}\right)^m = \frac{e^{-h^2}}{h\sqrt{\pi}} \frac{1}{1 - \frac{2}{e\theta}} \sim \frac{e^{-h^2}}{h}$$

Step 3 All such sets have zero measure:

$$e^{-h^2}/h \rightarrow 0 \text{ as } h \rightarrow \infty \quad \left[\text{but this corresponds to } \infty \right]$$

[discontinuity only ???]

Step 4 For discont. functions

$$|x(t_{j+1}) - x(t_j)| > h (t_{j+1} - t_j)^{\log_2 A} = h \left(\frac{j+1}{2^m} - \frac{j}{2^m} \right)^{\log_2 A}$$

$$= h \left(\frac{1}{2^m} \right)^{\log_2 A} = h 2^{-m \log_2 A} = h 2^{\log_2 A^{-m}} = h A^{-m}$$

[The last two steps of the proof are not clear!]

• Differentiable trajectories

$$|x(t_{j+1}) - x(t_j)| \underset{t_{j+1} \rightarrow t_j}{\leq} h(t_{j+1} - t_j) = \frac{h}{2^m}$$

The difference is only non zero in the interval for ξ_1, ξ_2 :

$$\int_{C[0,0;t]} d_W x(t) \cdot X[x(t)] = \int d\xi_1 d\xi_2 \frac{2^m}{\pi\sqrt{j}} e^{-\frac{2^m}{j}\xi_1^2} e^{-2^m(\xi_1 - \xi_2)^2}$$

$$|\xi_1 - \xi_2| < \frac{h}{2^m}$$

$$= \frac{2^{m/2}}{\sqrt{\pi}} \int dy e^{-y^2} = \frac{2}{\sqrt{\pi}} \int_0^{h/2^{m/2}} e^{-y^2} dy$$

$$|y| \leq \frac{h}{2^m} 2^{m/2} = \frac{h}{2^{m/2}}$$

As $m \rightarrow \infty$, $h/2^{m/2} \rightarrow 0$ and the $\int \rightarrow 0$ as well.
[Why?]

Conclusion: trajectories are continuous, but zig-zag like