

Itô Stochastic Differential Equations as 2-Jets

Drawing SDEs

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Outline

Aims:

- ▶ Give a coordinate free definition of a stochastic differential equation (SDE).
- ▶ Draw a picture of a stochastic differential equation

$$\begin{array}{ccc} \text{SDE for } X & \xrightarrow{\text{It\^o's lemma}} & \text{SDE for } f(X) \\ \text{Draw} \downarrow & & \text{Draw} \downarrow \\ \text{Picture of SDE for } X \text{ in } \mathbb{R}^n & \xrightarrow{f} & f(\text{Picture of SDE for } X) \end{array}$$

Analogy: Vector fields (ODEs) on manifolds can be defined in many ways: in coordinate charts; as first order approximations to curves; as operators satisfying certain algebraic properties.

Remarks

Other approaches to coordinate free definition of SDEs do exist:

- ▶ Use *Stratonovich calculus* to define SDEs on manifolds.
- ▶ Use *Schwartz-Morphisms* to define SDEs on manifolds.

Our approach has a number of applications:

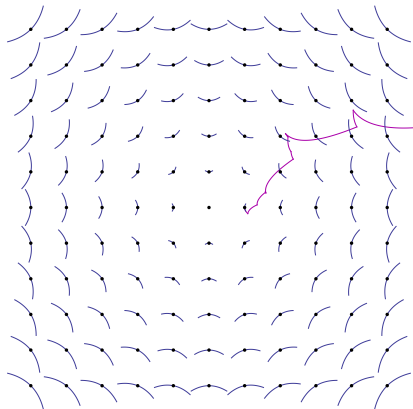
- ▶ Gives practical schemes for simulating SDEs on manifolds, which is useful in statistical estimation.
- ▶ Allows us to define a new notion of “projection” which can be used to obtain better low dimensional approximations to high dimensional SDEs.
- ▶ Visualisation of SDEs.

Stochastic Difference Equation

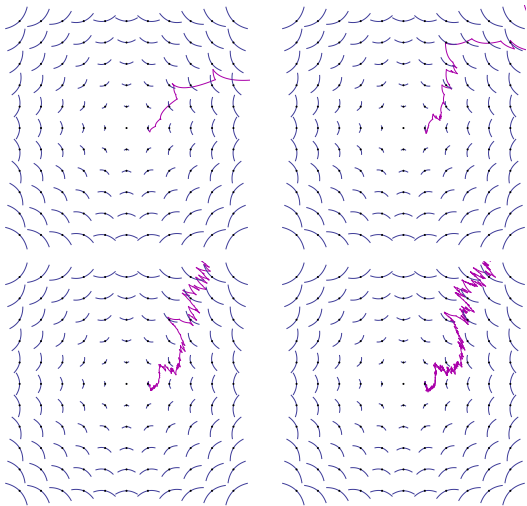
Let γ_x be a field of curves defined at each point of a manifold M .
Define a process by

$$X_0 := x_0, \quad X_{t+\delta t} := \gamma_{X_t}(W_{t+\delta t} - W_t). \quad (1)$$

where W_t is Brownian motion.



Take the limit as δt tends to 0



A coordinate free notion of convergence

What metric should we use?

- ▶ Classical: $E(|X_t - \tilde{X}_t|^2)$
- ▶ Coordinate free: “Mean square on compacts”. Motivation is that all Riemannian metrics are equivalent on compact sets.

Definition:

- ▶ Let K be a compact set in our manifold, g a Riemannian metric.
- ▶ Define \sim so that M/\sim is the one point compactification of the interior K^0 .
- ▶ Define a semi-metric

$$\tilde{d}^{g,K}([x], [y]) = \inf_{X \sim x, Y \sim y} d^g(X, Y).$$

- ▶ We have convergence in mean square on compacts if we have convergence in $E(\tilde{d}^{g,K}(X_t, \tilde{X}_t)^2)$ for all K and g .

Stochastic Differential Equation

If X_t is the limit as $\delta t \rightarrow 0$ then we write:

$$\text{Coordinate free SDE: } X_t \curvearrowright \gamma_{X_t}(dW_t), \quad X_0 = x_0.$$

Example

We take the manifold \mathbb{R} and define curves each point in \mathbb{R} by:

$$\gamma_x^\alpha(s) = x + s^\alpha$$

$$X_{n\delta t} = x_0 + \sum_{i=1}^n (W_{(i+1)\delta t} - W_{i\delta t})^\alpha = x_0 + (\delta t)^{\frac{\alpha}{2}} \sum_{i=1}^n \epsilon_i^\alpha$$

- ▶ When $\alpha=1$, $X_t = x_0 + W_t$
- ▶ When $\alpha=2$, $X_t = x_0 + t$
- ▶ When $\alpha \geq 3$, $X_t = x_0$

2-jets

We now break coordinate invariance and work in local coordinates.

- ▶ Taylor expansion

$$\delta X_t = \gamma'_{X_t}(0)\delta W_t + \frac{1}{2}\gamma''_{X_t}(0)(\delta W_t)^2 + R_{X_t}(\delta W_t)^3, \quad X_0 = x_0.$$

- ▶ The limit as $\delta t \rightarrow 0$ depends upon the first two terms.
- ▶ We only need the **2-jet** of the curve to define the SDE.

Definition

An n -jet is an equivalence class of smooth maps $f : M \rightarrow N$ between manifolds that are considered equal if the order n terms of their Taylor expansions are equal.

- ▶ ODE's correspond to one jets (vector fields)
- ▶ SDE's correspond to 2-jets of maps from $\mathbb{R}^k \rightarrow M$.

$$X_t \rightsquigarrow j_2(\gamma_{X_t}(dW_t)), \quad X_0 = x_0.$$

Itô calculus

We have the Taylor expansion

$$\delta X_t = \gamma'_{X_t}(0)\delta W_t + \frac{1}{2}\gamma''_{X_t}(0)(\delta W_t)^2 + R_{X_t}(\delta W_t)^3, \quad X_0 = x_0.$$

Our example calculation suggests $(\delta W_t)^2 \approx \delta t$

$$\delta X_t \approx \gamma'_{X_t}(0)\delta W_t + \frac{1}{2}\gamma''_{X_t}(0)\delta t \quad X_0 = x_0.$$

Defining $a(X) := \gamma''_{X_t}(0)/2$ and $b(X) := \gamma'_{X_t}(0)$:

$$\delta X_t = a(X_t)\delta t + b(X_t)\delta W_t.$$

it is well known that this Euler scheme converges to the solution of the Itô SDE

$$dX_t = a(X_t)dt + b(X_t)dW_t.$$

Note the use of the vector space structure of \mathbb{R}^n in this formulation.

Itô's lemma

Lemma

If $f : M \rightarrow N$ is smooth and the process X_t satisfies

$$X_t \curvearrowright j_2(\gamma_{X_t})(dW_t)$$

then $f(X_t)$ satisfies

$$f(X)_t \curvearrowright j_2(f \circ \gamma_{X_t})(dW_t).$$

Lemma

If $f : M \rightarrow N$ is smooth and the process X_t satisfies

$$dX_t^i = a^i(X_t)dt + b^i(X_t)dW_t$$

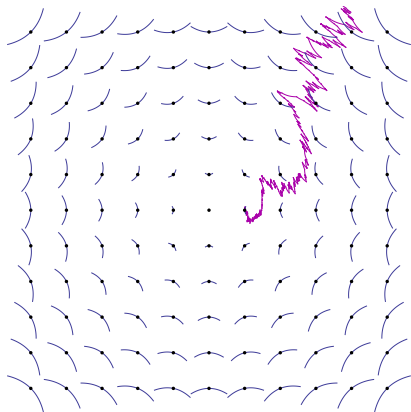
then $f(X_t)$ satisfies

$$\begin{aligned} df^i(X)_t = & \left(\sum_j \frac{\partial f^i}{\partial x^j} a^j(X, t) + \frac{1}{2} \sum_i \frac{\partial^2 f^i}{\partial x^j \partial x^j} (b^j(X, t))^2 \right) dt \\ & + \left(\sum_j \frac{\partial f^i}{\partial x^j} b^j(X, t) \right) dW_t \end{aligned}$$

(Classical formulation also requires technical bounds and Lipschitz conditions)

Itô's lemma example

$$\gamma_{(x_1, x_2)}^E(t) = (x_1, x_2) + t(-x_2, x_1) + 3t^2(x_1, x_2).$$



$$d(x_1, x_2) = \frac{3}{2}(x_1, x_2)dt + (-x_2, x_1)dW_t.$$

Itô's lemma example

If

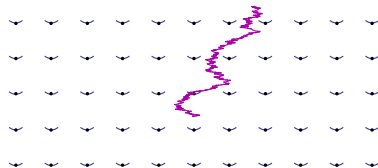
$$d(x_1, x_2) = 3(x_1, x_2)dt + (-x_2, x_1)dW_t.$$

and

$$f(\exp(s) \cos(\theta), \exp(s) \sin(\theta)) = (\theta, s),$$

by Itô's lemma $(\theta_t, s_t) = f((x_1, x_2))$ satisfies

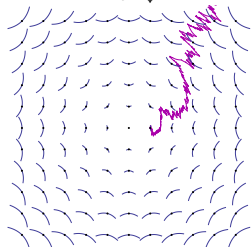
$$d(\theta, s) = \left(0, \frac{7}{2}\right)dt + (1, 0)dW_t. \quad (2)$$



Itô's lemma graphically

$$d(x_1, x_2) = 3(x_1, x_2)dt + (-x_2, x_1)dW_t$$

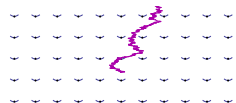
Draw ↓



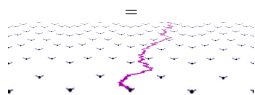
Itô's Lemma
→

$$d(\theta, s) = (0, \frac{7}{2})dt + (1, 0)dW_t$$

Draw ↓

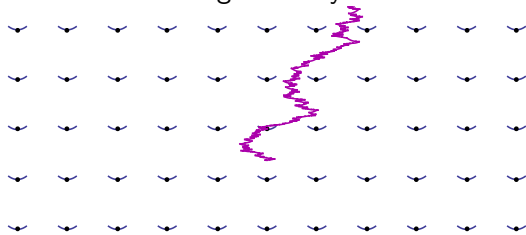


Transform
→

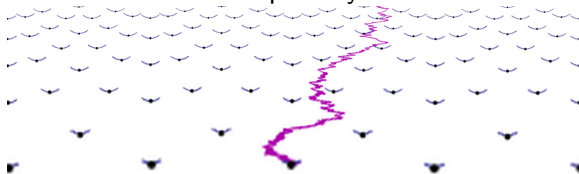


Transforming algebraically and graphically

Algebraically



Graphically



Coordinate free stochastic differential geometry

- ▶ If

$$\gamma_x : \mathbb{R}^k \rightarrow M$$

is an SDE and $f : M \rightarrow \mathbb{R}$ is a smooth function define

$$\mathcal{L}_x f = \frac{1}{2} \Delta (f \circ \gamma_x).$$

This is the *backward diffusion operator*. It acts on functions.

- ▶ For compact M , we have a pairing between densities ρ and functions f given by

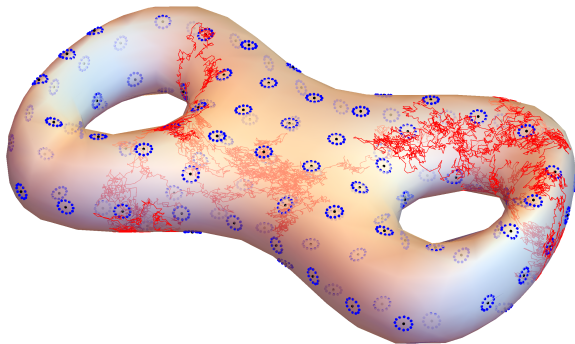
$$\int_M f \rho.$$

We can define \mathcal{L}^* to be the formal adjoint of \mathcal{L} with respect to this pairing. This is the *forward diffusion operator*, it acts on densities.

- ▶ γ_x defines *Brownian motion* on a Riemannian manifold if $\mathcal{L} = \frac{1}{2} \Delta_g$.

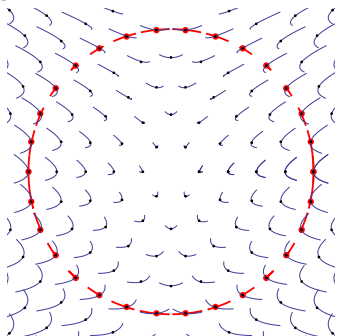
Applications - Simulating SDEs on manifolds

The classical Euler scheme is a poor choice for simulating SDEs on manifolds as one rapidly leaves the manifold. By choosing the curves γ to closely follow a manifold, one can obtain simulations that stay close to the manifold.



Applications - Projection

It is intuitively clear how to project an SDE onto a manifold in the jet formulation. This gives a different notion of projection than that obtained using Stratonovich calculus and which is in a clearly defined sense superior to Stratonovich projection as a method for approximating SDEs.



Stratonovich calculus and jets

- ▶ *Stratonovich calculus* is an alternative to Itô calculus which allows you to define SDEs using vector fields.
- ▶ Given a vector field A , let Φ_A^t be the family of diffeomorphisms obtained by flowing along A for time t .
- ▶ Given two vector fields A and B , define

$$\gamma_x(t) = \Phi_A^{t^2} \circ \Phi_B^t(x).$$

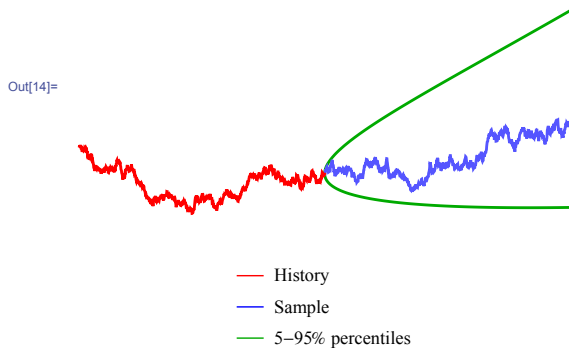
- ▶ This SDE is equivalent to the classical Stratonovich SDE

$$\circ dX_t = A(X_t)dt + B(X_t) \circ dW_t.$$

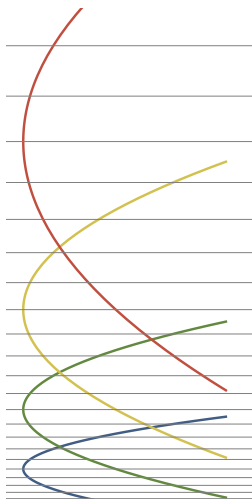
- ▶ Thus Stratonovich calculus can be interpreted simply as giving an alternative parameterization of a field of curves to the parameterization of Itô calculus.

Jets and fan diagrams

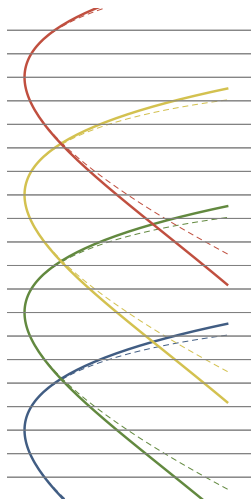
Another way of drawing an SDE is a fan diagram



Brownian motion and Geometric Brownian motion



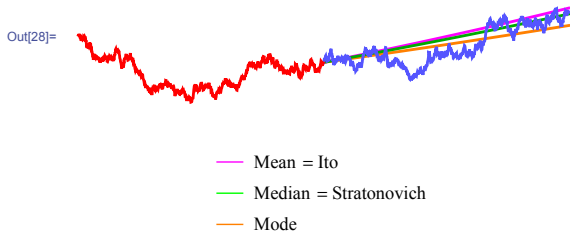
Geometric Brownian Motion



Brownian Motion

Fan diagrams at the percentiles $\pm\Phi(1)$

Mean, Median, Mode



Summary

- ▶ The language of 2-jets allows us to formulate stochastic differential equations in a coordinate free manner.
- ▶ Itô's lemma has the simple interpretation of composition of functions
- ▶ One can visualize stochastic differential equations
- ▶ These visualization tools show statistically interesting features of the SDE

