

Computational modeling

Lecture 9 : The Tacoma Bridge

Physics:

The *Tacoma* bridge

Programming:

Code explained

Instructor : Cedric Weber

Course : 4CCP1000

Today we write a model for ...



Tacoma Bridge

- ❑ Shortly after its construction in July, it was discovered that the bridge would sway and buckle dangerously in windy conditions.
- ❑ The failure of the bridge occurred when a torsional twisting mode occurred.
- ❑ The bridge's spectacular self-destruction is often used as an object lesson in the necessity to consider both aerodynamics and resonance effects
- ❑ Luckily : only one car was on the bridge at this time. The passenger was injured but alive. The only casualty was his dog.



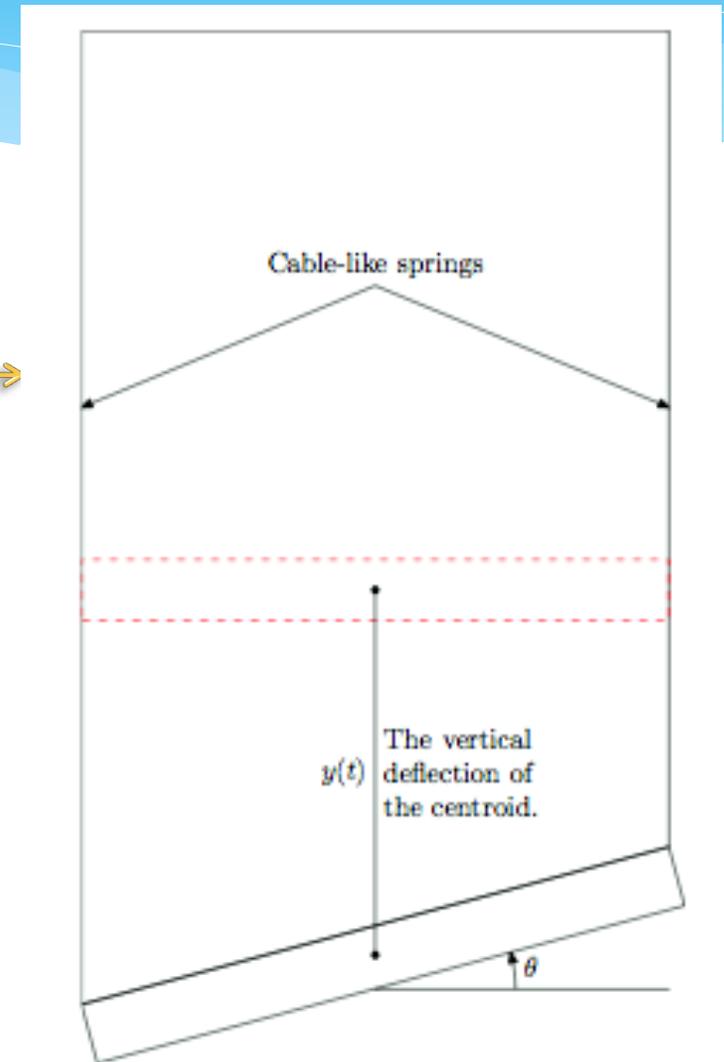
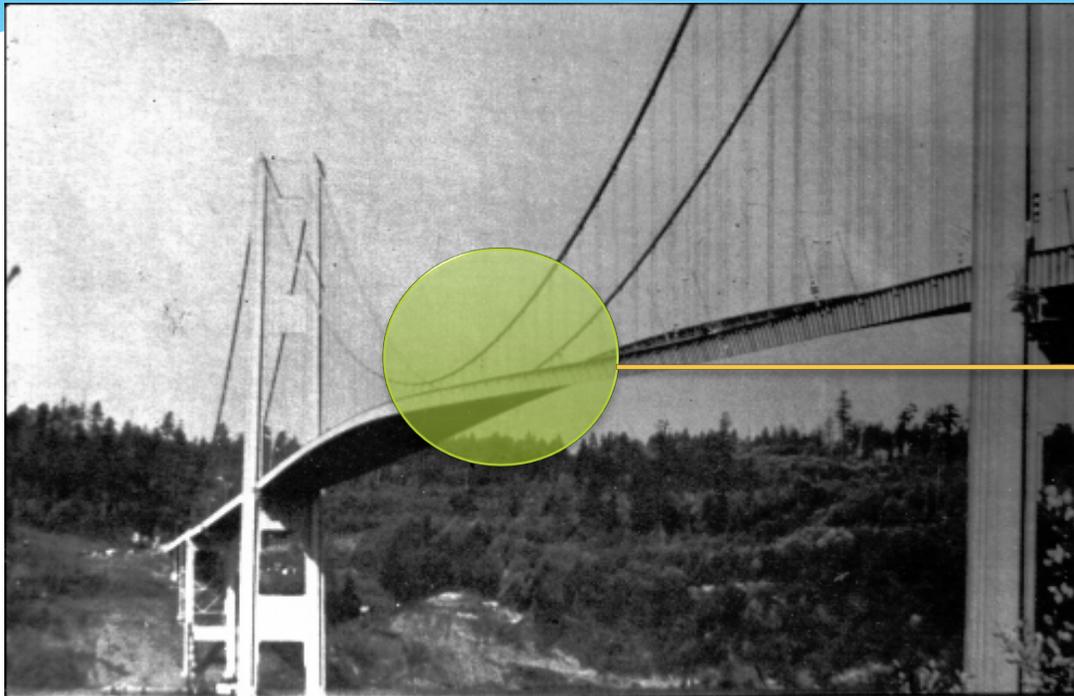
* Reference: Numerical analysis / Timothy Sauer

Tacoma Bridge



Tacoma bridge

- * Simple model, we take a slice of the bridge, suspended by two cables :



- * From the movie, can you identify which are the relevant parameters ?
- * What type of oscillations do we need to describe ?

Simple model, two variables

□ Consider a **roadway of width $2 \cdot l$** suspended by two cables

□ We model the dynamic of the bridge with two functions, $y(t)$ and $\theta(t)$.

□ θ = torsion angle

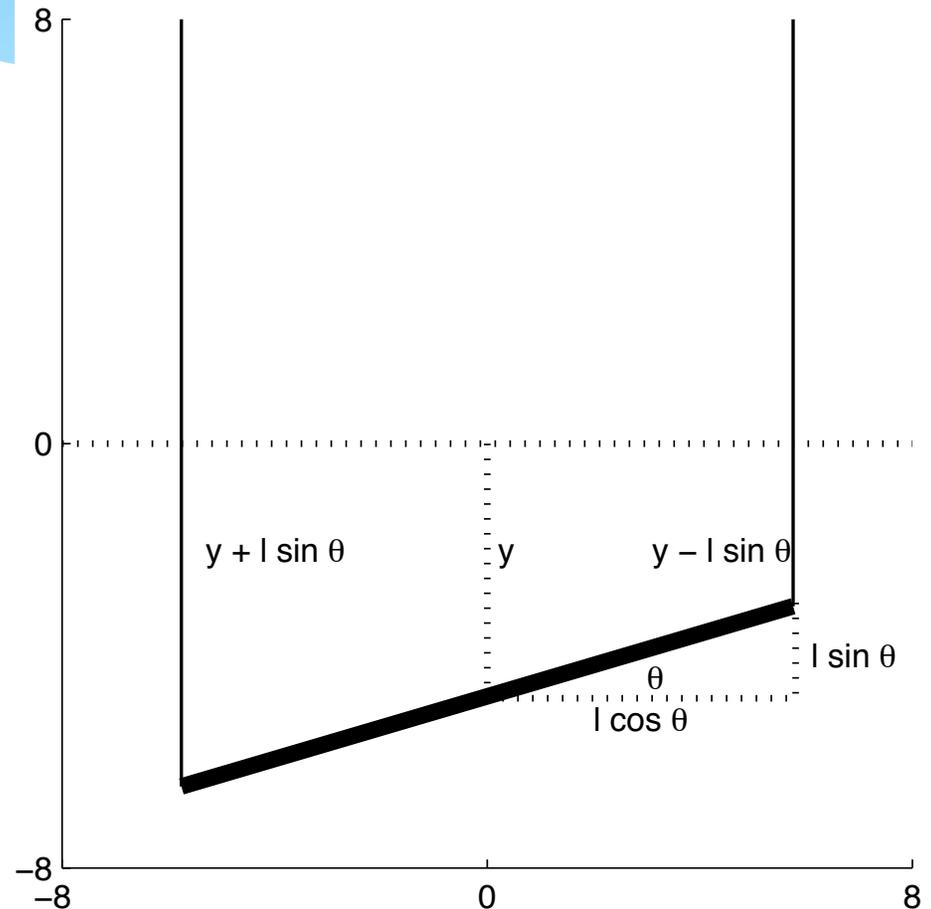
□ y = vertical elevation

□ Rest position : $\theta=0$, $y=0$

□ Hooke's law : restoring force in the cables will be proportional to y

□ There are two suspension cables, stretched from equilibrium by :

$$y - l \sin \theta \quad \text{and} \quad y + l \sin \theta$$



Modeling the bridge oscillations

$d * y'$, d is a coefficient

□ Differential equations:

$$y'' = \textcircled{-dy'} - \left[\frac{K}{m}(y - l \sin \theta) + \frac{K}{m}(y + l \sin \theta) \right]$$

$$\theta'' = \textcircled{-d\theta'} + \frac{3 \cos \theta}{l} \left[\frac{K}{m}(y - l \sin \theta) - \frac{K}{m}(y + l \sin \theta) \right]$$

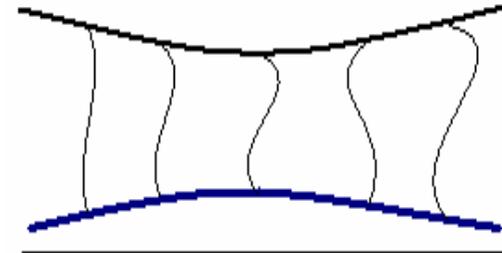
□ K is the Hook's constant ($F=Kx$, where x is displacement, as in a spring)

□ d : dissipative constant [$d*y'$ and $d*\theta'$: dissipative terms]

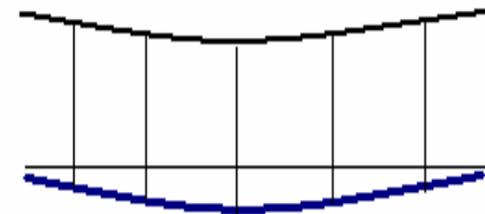
Cables described by springs ?

- * Modelling the cable as spring, is it realistic ?
- * Minor modification: Hook's spring law was used here, but indeed the cables of the bridge are not like a spring. They do not have a strong resistance once compressed.
- * We replace the Hook's terms with a similar term, but which only has resistance in one direction :

$$f(y) = (K/a)(e^{ay} - 1)$$



Cables slack because roadbed is above rest position



Cables taut, roadbed below rest position

Tacoma bridge equations

- * We obtain the final differential equations:

$$y'' = -dy' - \frac{K}{ma} \left[e^{y-l \sin \theta} - 1 + e^{y+l \sin \theta} - 1 \right]$$
$$\theta'' = -d\theta' + \frac{3 \cos \theta}{l} \frac{K}{ma} \left[e^{y-l \sin \theta} - e^{y+l \sin \theta} \right].$$

- * We start at equilibrium (no wind, bridge stable): $(y, \theta) = (0, 0)$
- * Now we turn on the wind, this adds the following term to the right hand side of the $y(t)$ equation (the wind is modeled by a periodic Force):

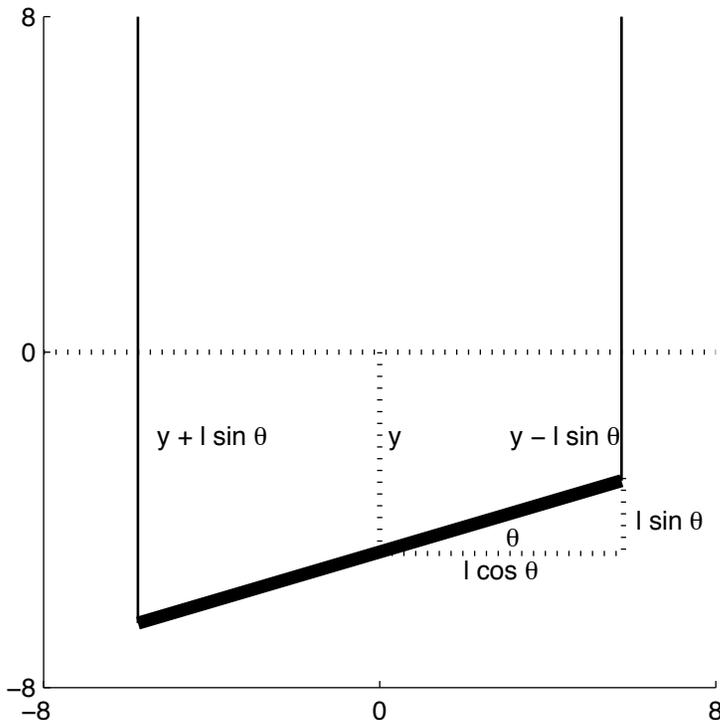
$$A \sin \omega t$$

- * **Practice session:** modify the pendulum code to treat these two coupled second order differential equation. Understand what is the reason why the Tacoma bridge collapsed.

Tacoma bridge

$$y'' = -dy' - \frac{K}{ma} \left[e^{y-l \sin \theta} - 1 + e^{y+l \sin \theta} - 1 \right]$$

$$\theta'' = -d\theta' + \frac{3 \cos \theta}{l} \frac{K}{ma} \left[e^{y-l \sin \theta} - e^{y+l \sin \theta} \right].$$



- * Initial condition : $(y, \theta) = (0, 0)$
 $(y', \theta') = (0, 0)$
- * Now we turn on the wind, this adds to the right hand side of the $y(t)$ equation :

$$A \sin \omega t$$

Reminder : coupled first order equations, quantum mechanics

- * We discussed in the last lecture that this equation can be decomposed in two coupled first order equations:

$$\boxed{\frac{d^2 y(x)}{dx^2} = -E y(x)}$$

Initial conditions

$$y(0) = 0 \quad y'(0) = 0$$

- * Simple idea: let's define a new variable:

$$\left\{ \begin{array}{ll} \frac{dy}{dx} = z & z(0) = 1 \\ \frac{dz}{dx} = -E y & y(0) = 0 \end{array} \right.$$

- * We get the equations :

System of first order equations, Tacoma bridge

* We go from :

$$\begin{aligned} y'' &= -dy' - \frac{K}{ma} \left[e^{y-l\sin\theta} - 1 + e^{y+l\sin\theta} - 1 \right] \\ \theta'' &= -d\theta' + \frac{3\cos\theta}{l} \frac{K}{ma} \left[e^{y-l\sin\theta} - e^{y+l\sin\theta} \right]. \end{aligned}$$

* to

$$\left\{ \begin{aligned} \frac{dy}{dx} &= z \\ \frac{dz}{dx} &= \textcircled{-dz} - \frac{K}{ma} (e^{y-l\sin\theta} + e^{y+l\sin\theta} - 2) \\ \frac{d\theta}{dx} &= \gamma \\ \frac{d\gamma}{dx} &= -d\gamma + \frac{3K\cos\theta}{lma} (e^{y-l\sin\theta} - e^{y+l\sin\theta}) \end{aligned} \right.$$

d * z, d is a coefficient

System of first order equations, Functions F1,F2,F3,F4

* We go from :

$$\begin{aligned} y'' &= -dy' - \frac{K}{ma} \left[e^{y-l\sin\theta} - 1 + e^{y+l\sin\theta} - 1 \right] \\ \theta'' &= -d\theta' + \frac{3\cos\theta}{l} \frac{K}{ma} \left[e^{y-l\sin\theta} - e^{y+l\sin\theta} \right]. \end{aligned}$$

* To :

$$\begin{cases} \frac{dy}{dx} = F_1(y, z, \theta, \gamma) \\ \frac{dz}{dx} = F_2(y, z, \theta, \gamma) \\ \frac{d\theta}{dx} = F_3(y, z, \theta, \gamma) \\ \frac{d\gamma}{dx} = F_4(y, z, \theta, \gamma) \end{cases} \quad \text{With :}$$

$$\begin{aligned} F_1(y, z, \theta, \gamma) &= z \\ F_2(y, z, \theta, \gamma) &= -dz - \frac{K}{ma} (e^{y-l\sin\theta} + e^{y+l\sin\theta} - 2) \\ F_3(y, z, \theta, \gamma) &= \gamma \\ F_4(y, z, \theta, \gamma) &= -d\gamma + \frac{3K\cos\theta}{lma} (e^{y-l\sin\theta} - e^{y+l\sin\theta}) \end{aligned}$$

Wind force

* The wind add a contribution to $y''(x)$:

$$\begin{aligned}\frac{dy}{dx} &= F_1(y, z, \theta, \gamma) \\ \frac{dz}{dx} &= F_2(y, z, \theta, \gamma) \\ \frac{d\theta}{dx} &= F_3(y, z, \theta, \gamma) \\ \frac{d\gamma}{dx} &= F_4(y, z, \theta, \gamma)\end{aligned}$$



$$\begin{aligned}\frac{dy}{dx} &= F_1(y, z, \theta, \gamma) \\ \frac{dz}{dx} &= F_2(y, z, \theta, \gamma) + A\sin(\omega x) \\ \frac{d\theta}{dx} &= F_3(y, z, \theta, \gamma) \\ \frac{d\gamma}{dx} &= F_4(y, z, \theta, \gamma)\end{aligned}$$

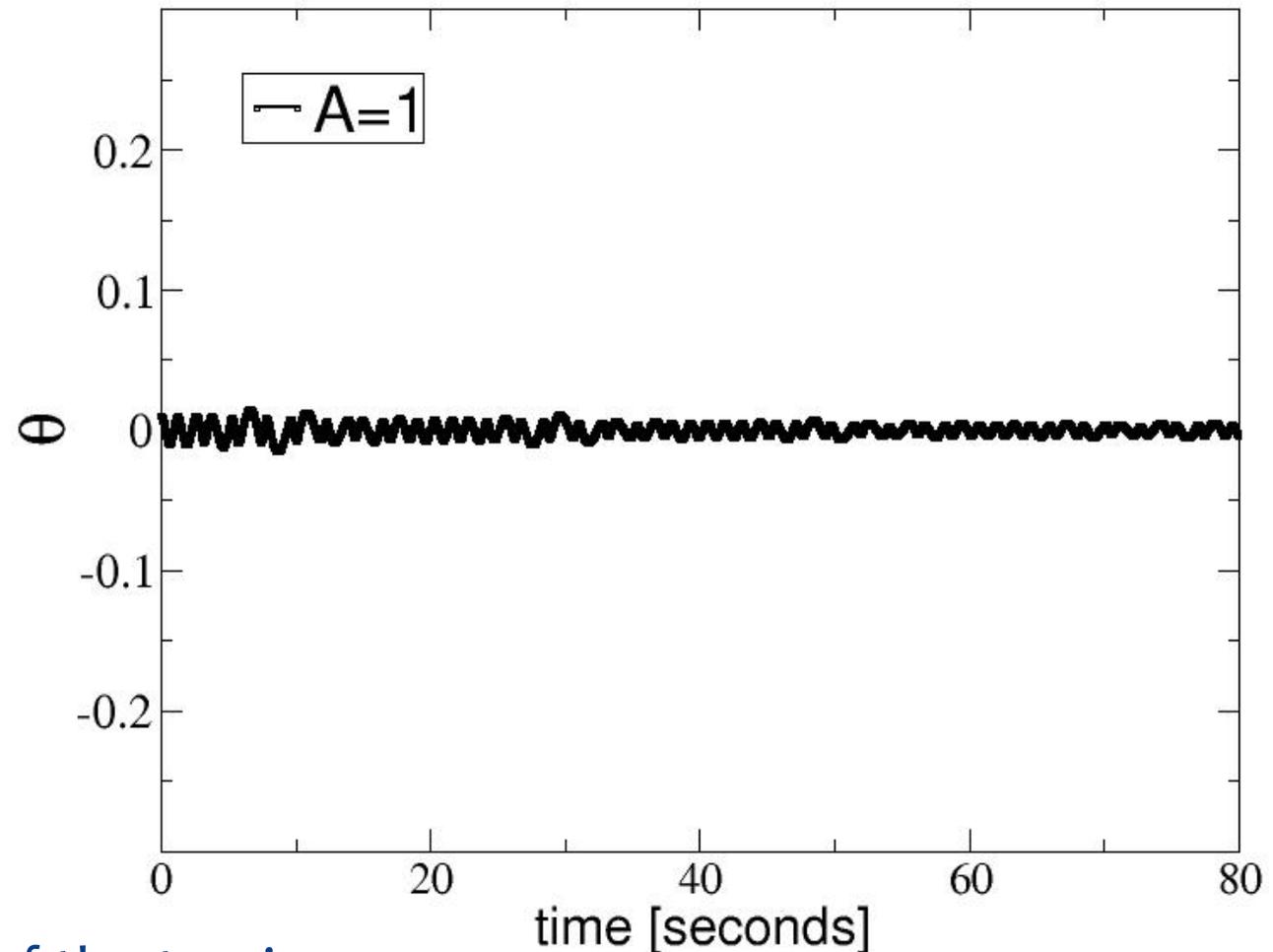
Physical parameters

- ❑ M (mass of bridge) : **M = 2500 Kg**
- ❑ Spring constant : **K = 1000 Newtons**
- ❑ Hooke's coefficient : **a = 0.1**
- ❑ Roadway 12 meters wide : **l=12 m**
- ❑ Friction coefficient : **d = 0.01**
- ❑ Vertical force due to the wind caused the bridge to oscillate once every 2 seconds, so :
 $\omega = 2 \pi / 2 \sim 3$

We study the effect of the force amplitude of the wind : A

Moderate wind, $A=1$

Moderate
wind, torsion
is controlled,
small
oscillations

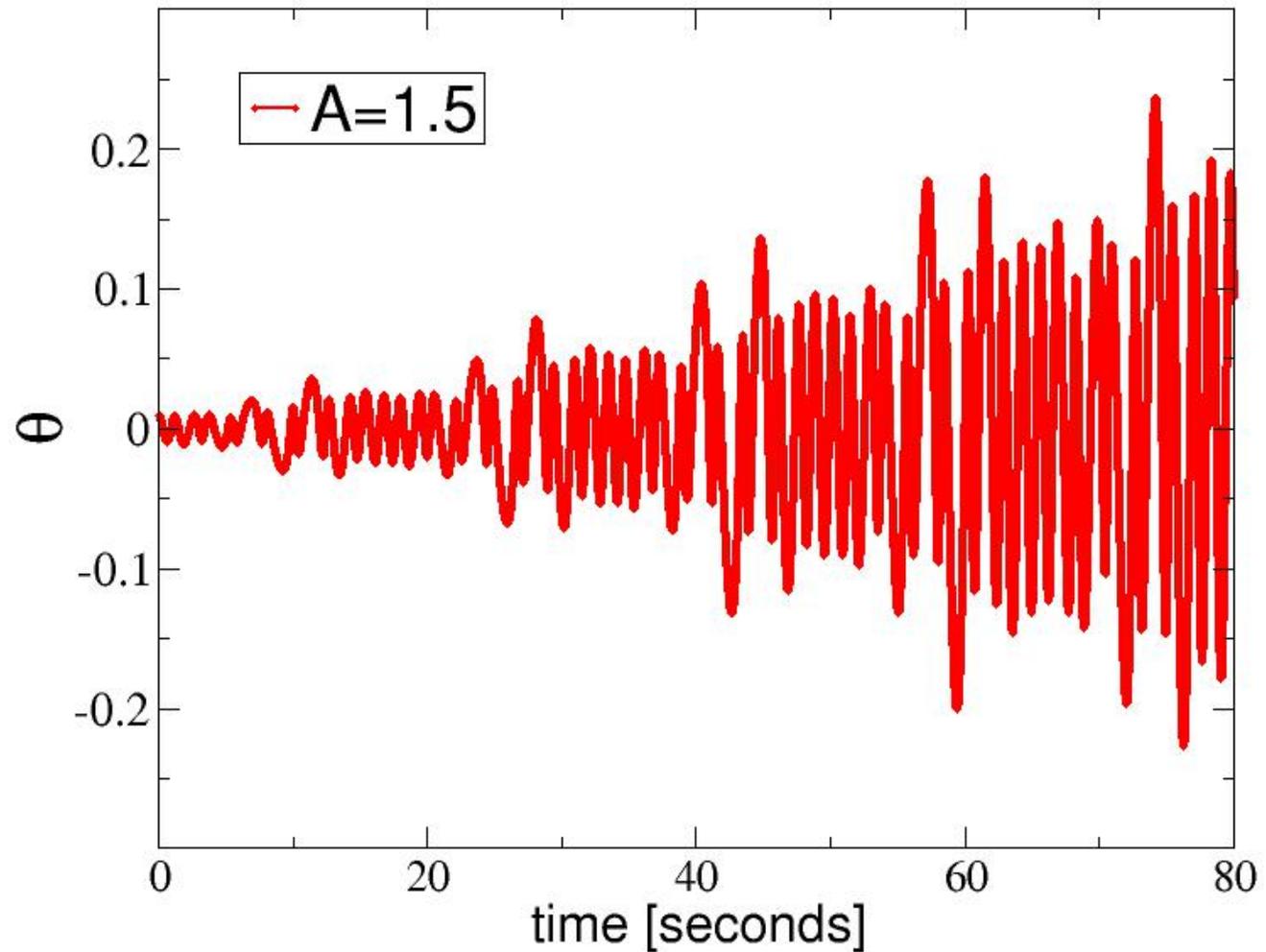


* Time dependence of the torsion

Strong wind, $A=1.5$

Stronger wind,
torsion is
uncontrolled, it
gets larger and
larger

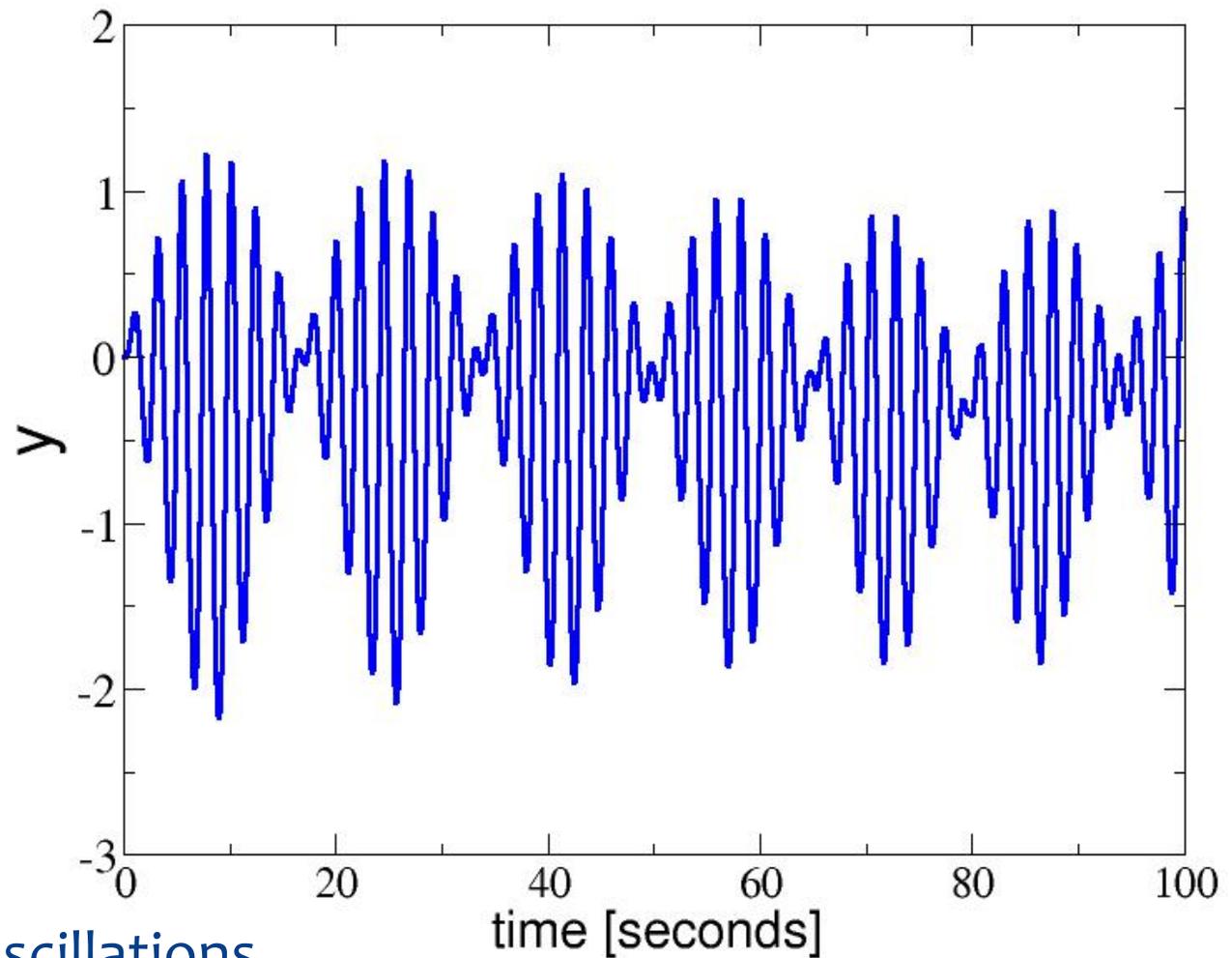
→ Tacoma's
breakdown



* Time dependence of the torsion

Strong wind, $A=1.5$

Note that the vertical amplitude are controlled, they are not dramatic, the Takoma bridge broke because of the torsion!



* Vertical amplitude oscillations

module library

```
real(8), parameter :: d=0.01, K=1000.0, a=0.1, l=6.0, m=2500
```

contains

```
function F1 ( y , z , t , g )  
implicit none  
real(8) :: F1  
real(8) :: y , z , t , g  
  F1 = z  
end function
```

```
function F2(y,z,t,g)  
implicit none  
real(8) :: F2  
real(8) :: y,z,t,g  
  F2 = ..... [ FILL IN ] .....  
end function
```

```
function F3(y,z,t,g)  
implicit none  
real(8) :: F3  
real(8) :: y,z,t,g  
  F3 = g  
end function
```

```
function F4(y,z,t,g)  
implicit none  
real(8) :: F4  
real(8) :: y,z,t,g  
  F4 = ..... [FILL IN].....  
end function
```

end module



Code explained: F1,F2,F3,F4 functions

$$\begin{aligned} F_1(y, z, \theta, \gamma) &= z \\ F_2(y, z, \theta, \gamma) &= -dz - \frac{K}{ma} (e^{y-l\sin\theta} + e^{y+l\sin\theta} - 2) \\ F_3(y, z, \theta, \gamma) &= \gamma \\ F_4(y, z, \theta, \gamma) &= -d\gamma + \frac{3K\cos\theta}{lma} (e^{y-l\sin\theta} - e^{y+l\sin\theta}) \end{aligned}$$

Code explained : Taylor's method

```

program tacoma
use library
implicit none
integer,parameter      :: N=100000
integer                :: j
real(8)                :: h,tinitial,tfinal,Amp
real(8)                :: x(0:N),y(0:N),z(0:N),t(0:N),g(0:N)

tinitial=0.0 ;   tfinal=100.0 ;   h = (tfinal - tinitial) / dble(N)

write(* ,*) 'please enter Wind force amplitude'
read(* ,*)  Amp

x(0)=0
y(0)  =...[FILL IN]...
z(0)  =...[FILL IN]...
t(0)  =...[FILL IN]...
g(0)  =...[FILL IN]...

do j = 1, N
  x(j)  = j*h
  y(j)  = y(j-1) + h * F1 (y(j-1),z(j-1),t(j-1),g(j-1))
  z(j)  = z(j-1) + h * ( F2 (y(j-1),z(j-1),t(j-1),g(j-1)) + Amp * ... [FILL IN] )
  t(j)  = t(j-1) + h * F3 (y(j-1),z(j-1),t(j-1),g(j-1))
  g(j)  = g(j-1) + h * F4 (y(j-1),z(j-1),t(j-1),g(j-1))

  ! vertical amplitude y
  write(100,*) x(j), ..... [FILL IN].....
  ! torsion theta
  write(101,*) x(j), ..... [FILL IN].....

enddo
end program

```

Initial conditions?



Wind?



Writing solutions into
Two different files?

1. define the initial and final time
2. define the initial conditions
3. we start with a small torsion $t(0) = 0.01$
4. we solve the four coupled differential equations with the Taylor's method
5. we write the vertical amplitude $y(j)$ and the torsion $t(j)$ obtained at time $x(j)$ into the files : fort.100 and fort.101

Problem

- **Problem 1**: Oscillation modes of the Tacoma bridge